

ITERATIVE DECONVOLUTION OF X-RAY
AND OPTICAL SNR IMAGES

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Iterative Deconvolution of X-ray and Optical SNR Images

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1 Introduction

Blind Iterative Deconvolution (BID) is a technique which was originally developed to correct the degrading effects of atmospheric turbulence on astronomical images from single short exposure, high signal-to-noise-ratio frames. At the Center for Astrophysics, we have implemented a version of BID following the general approach of Ayers and Dainty (1988), but extending the technique to use Wiener filtering (Nisenson et al, 1990) and developed it for application to high energy images from Einstein and ROSAT. In the optical, the point spread function (psf) that degrades the images is due to a combination of telescope and atmospheric aberrations. At high energies, the degrading function is the instrument response function, which is known to be time and energy level unstable. In both cases the psf is poorly known, so BID can be used to extract the psf from the image and then deconvolve the blurred image to produce a sharpened image.

BID follows the general approach of constrained iterative techniques such as those developed for phase retrieval (Gerchberg and Saxton, 1972; Fienup, 1978) with blind deconvolution (Lane and Bates, 1987). One starts with an image which is degraded by some blurring function (i.e. the point spread function or psf). A necessary condition for the algorithm to work is that the blurring function be invariant over the entire restored image field (stationarity), and we note that the degradation is purely a linear operation. The general approach in the algorithm is to find a pair of functions whose convolution gives the input data within a set of physical constraints. The most important constraint requires that both the image and the psf be positive. When the data is noisy, this will not be strictly true, but minimizing the negativity in the solution appears to be sufficient in almost all cases. Another constraint is applied by defining a "support" region in image space where the image (or psf) is non-zero, and then resetting that area to zero after each iteration. Finally, the signal-to-noise ratio in the Fourier transform (FT) of the image or psf constrains the dynamic range of the deconvolution operation by using a Wiener filter for the deconvolution operation. While it has not been proven that the restored images from BID are unique, complicated images appear to converge on only one sensible solution.

2 Implementation

A flow diagram for the technique is given in figure 1. One starts with a degraded image and an initial estimate of the point spread function (psf). The initial psf can be randomly chosen, however the number of iterations required for the algorithm to converge is highly dependant on how close the first estimate of the psf is to the actual psf. Both inputs are Fourier transformed and a deconvolution is performed by constructing a Wiener filter from the FT of the psf and an estimate of the noise in the image spectrum. The technique of Wiener (or Optimum) filtering damps the high frequencies and minimizes the mean square error between each estimate and the true spectrum.

The Weiner filtering spectrum, $o_f(u, v)$, usually takes the form:

$$o_f(u, v) = o(u, v) \cdot \frac{p^*(u, v)}{|p(u, v)|^2 + |n(u, v)|^2} \quad (1)$$

$o(u, v)$, $p(u, v)$ and $n(u, v)$ are the object, PSF and noise spectra respectively. For white noise, $n(u, v)$ usually can be replaced with a constant estimated as the rms fluctuation of the high frequency region in the object spectrum (i.e. at frequencies where the object power is negligible).

The result after Wiener filtering is transformed back to image space and positivity and support constraints are applied. The negatives in the image are set to zero and their total value summed. This value is divided by the number of pixels inside the support region and subtracted within that region in order to preserve the total power in the image. After subtraction, some areas of the image may become negative. If this is the case, the negatives are again truncated, summed and subtracted. This procedure is repeated until the negatives in the restored image are reduced to a negligible level. The original degraded image is then deconvolved by the restored image obtained from the first iteration. The result is transformed back to image space. Again, positivity and support constraints are enforced. The result is a new estimate of the psf. The iteration continues until a stable solution is found. A damping factor is used to stabilize the iteration, particularly important when the psf estimate is still inaccurate. About 20% of the image (or psf) from the previous cycle is averaged with the new image (or psf) in the early stages of the process. This percentage is reduced when the iteration has nearly converged.

Two criterion have been found to be very useful in determining the completion of the iterations: the ratio of positive power to negative power in the restored image and psf; and the rms difference between images or psfs from successive iterations. Both criteria drop irregularly in the first few cycles of the iteration, but they both level off and stabilize when the operation is close to convergence. After examination of the output image and the psf, the results may be fed back into the loop for continued iterations.

There are a number of parameters which must be chosen in order to ensure convergence and an optimum result. Probably the most important are accurately estimating the signal-to-noise ratio in the data, allowing construction of the Wiener filter, and carefully defining the region for the support constraint. It is also very important that the image and psf remain aligned with the support, since truncation seriously degrades the process. This is done by centering the initial image and psf, calculating the two support regions, and then recentering the psf after each cycle.

Appendix A contains listings of the software developed for BID. It consists of four packages: the main program (bid.f), a collection of subroutines used by BID (bidsubs.f), a set of subroutines used to interface with the IRAF data reduction package (irafsubs.f), and a multi-dimensional fast fourier transform (fourtf.f). Each of the packages has internal documentation that describes the functions of each routine and aids the selection of parameters when running the program. This choice of parameters is highly dependant on the data that is to be deconvolved, and it must be tuned by the user through experience. However, suggested starting values are provided that should help initially. Also included is wiener deconvolution program that can be used after BID has found the psf. Reinsertion of the original data and the psf from BID into DCW (dcw.f) allows deconvolution of the image with an adjustable low-pass filter and a choice of wiener filter parameter to produce smoother or sharper reconstructions. Once the psf has been found, the signal-to-noise ratio in the data determines the frequency range and enhancement level acceptable in the deconvolved image. The programs must be compiled inside IRAF using the FC compiler command.

3 Einstein X-ray Images

We have applied BID to an extensive set of supernova remnants from the Large Magellanic Cloud. The results have varying success, mostly depending on the signal-to-noise ratios in the raw data. In the very low surface brightness SNR's, the result is not much more than a quasi-optimum smoothing. All deconvolved images were produced using the same parameters in BID (to find the psf) and then in DCW to produce the image: we used the parameters suggested in the BID program and we ran BID with the psf support-only option. In DCW, we used a frequency cutoff of 1.0 (the maximum value) and a wiener filter multiplier of 4.0. Some of the images could be restored with smaller wiener multipliers (producing a sharper image) but we show only the results for this one value to allow comparison between data sets.

Figures 1 and 2 are for Cyg X-1. The deconvolved image is point-like with the elongation seen in the raw data (figure 1), presumably due to aberrations removed. DEM71 is an extended low surface brightness remnant. The deconvolved image (Figure 4) is only a somewhat smoothed version of the input, unsurprising for the low signal-to-noise ratio in the raw image (Figure 3). N23 is another extended remnant. Here the deconvolved image (Figure 6) has sharpened and defined the bright knots, allowing a better feeling for the structural detail than in the raw data (Figure 5). The results for N49, N49B, N63A and N132 (Figures 7-14) are similar to N23: some improvement in definition of the brighter features and an overall smoothing of the images allowing easier interpretation.

Figures 15 and 16 show the data and deconvolution for the results obtained for N103B. In this case, the data are believed to suffer from image motion in the up-down direction, giving the image its double lobed appearance. The deconvolution has partially compensated for this, substantially brightening the lower "lobe". However, image motion is difficult to completely remove without very high signal-to-noise ratios since its transfer function drops rapidly to zero.

Figures 17 and 18 show the input image and deconvolution for SNR0102, a circular ring remnant, seen almost face-on. The deconvolution shows a number of interesting features including a number of bright knots and asymmetries in the ring. Particularly striking is the

dark break in the ring near the top of the image. The raw data shows hints of this feature, but it is cleanly defined in the reconstruction.

Figures 19 and 20 produce what is perhaps the most perplexing result from the SNR0519. This is a rather small SNR, appearing rather amorphous in the raw data, however the deconvolution produces a very different result: a bright central peak with a small bright region, all sitting on a fainter extended remnant. This data was run for several hundred extra cycles and with different random starting psf's. In all cases the results were the same. The image in figure 20 is after 200 iterations of BID, very nearly the same result as the 100 iteration output. Further analysis will be required to determine whether the result is real or whether some special problem with data produced it. This is the only result that does not appear to be consistent with the original data.

Figures 21 and 22 show the results for SNR0540, a very compact remnant. The data and the deconvolution show a very bright central core and some extend flux around the SNR. Figures 23 and 24 present two other data displays of the deconvolution, a contour plot and a surface plot. These displays hint at a flattening of the central core, possibly corresponding to the ring seen in optical images. Since it is only a few pixels wide, it would be difficult to conclude the exact nature of the flattening.

These results demonstrate the capabilities and the limitation of the BID program. In all cases, the results appear to be stable, and in all cases but one, consistent with original data. For data with higher signal-to-noise ratio, substantial sharpening of the image features is obtained. For the very low surface brightness images, the result is close to an optimally smoothed result.

4 Summary

BID appears to be a powerful new tool for high angular resolution astronomy. While the technique requires fairly high signal-to-noise ratios in the data, substantial improvement in image sharpness can be obtained even for low flux x-ray images. The programs are relatively easy to use, interfacing with the IRAF package to allow reading and writing IRAF images.

5 References

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- Fienup, J.R. 1978, *Opt. Lett.*, **3**, 27.
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Karovska, M. and Habbal, S. 1991, *Ap. J.*, **37**,

Lane, R.G. and Bates, R.H.T. 1987, *J. Opt. Soc. Am. A*, **4**, 180.

Nisenson, P., Standley, C. and Gay, D. 1990, *Proceedings of Space Telescope Science Institute Workshop on HST Image Processing*, Baltimore, Md.

Figure Captions

- Figure (1) - Einstein Data for Cyg X-1
- Figure (2) - BID Deconvolution for Cyg X-1
- Figure (3) - Einstein data for DEM71
- Figure (4) - Bid Deconvolution for DEM71
- Figure (5) - Einstein Data for N23
- Figure (6) - BID Deconvolution for N23
- Figure (7) - Einstein data for N49
- Figure (8) - Bid Deconvolution for N49
- Figure (9) - Einstein Data for N49B
- Figure (10) - BID Deconvolution for N49B
- Figure (11) - Einstein data for N63A
- Figure (12) - Bid Deconvolution for N63A
- Figure (13) - Einstein data for N103B
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- Figure (15) - Einstein Data for N132D
- Figure (16) - BID Deconvolution for N132D
- Figure (17) - Einstein Data for SNR0102
- Figure (18) - BID Deconvolution for SNR0102
- Figure (19) - Einstein data for SNR0519
- Figure (20) - Bid Deconvolution for SNR0519
- Figure (21) - Einstein Data for SNR0540
- Figure (22) - BID Deconvolution for SNR0540
- Figure (23) - Contour Plot of the BID Deconvolution of SNR0540
- Figure (24) - Surface Plot of the BID Deconvolution of SNR0540

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cygx1gzm

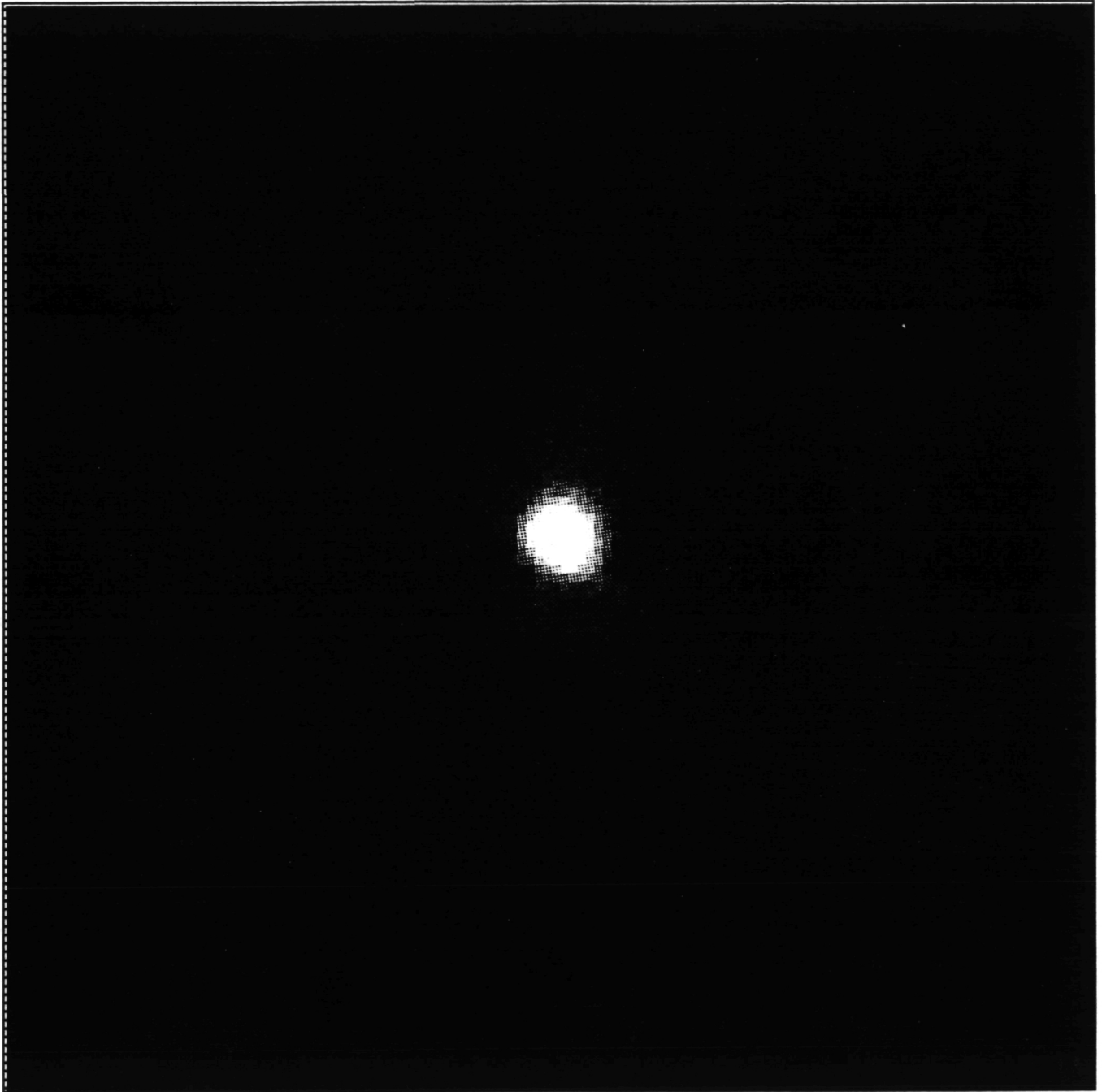


Figure (1) - Einstein Data for Cyg X-1

cygx1d300w4

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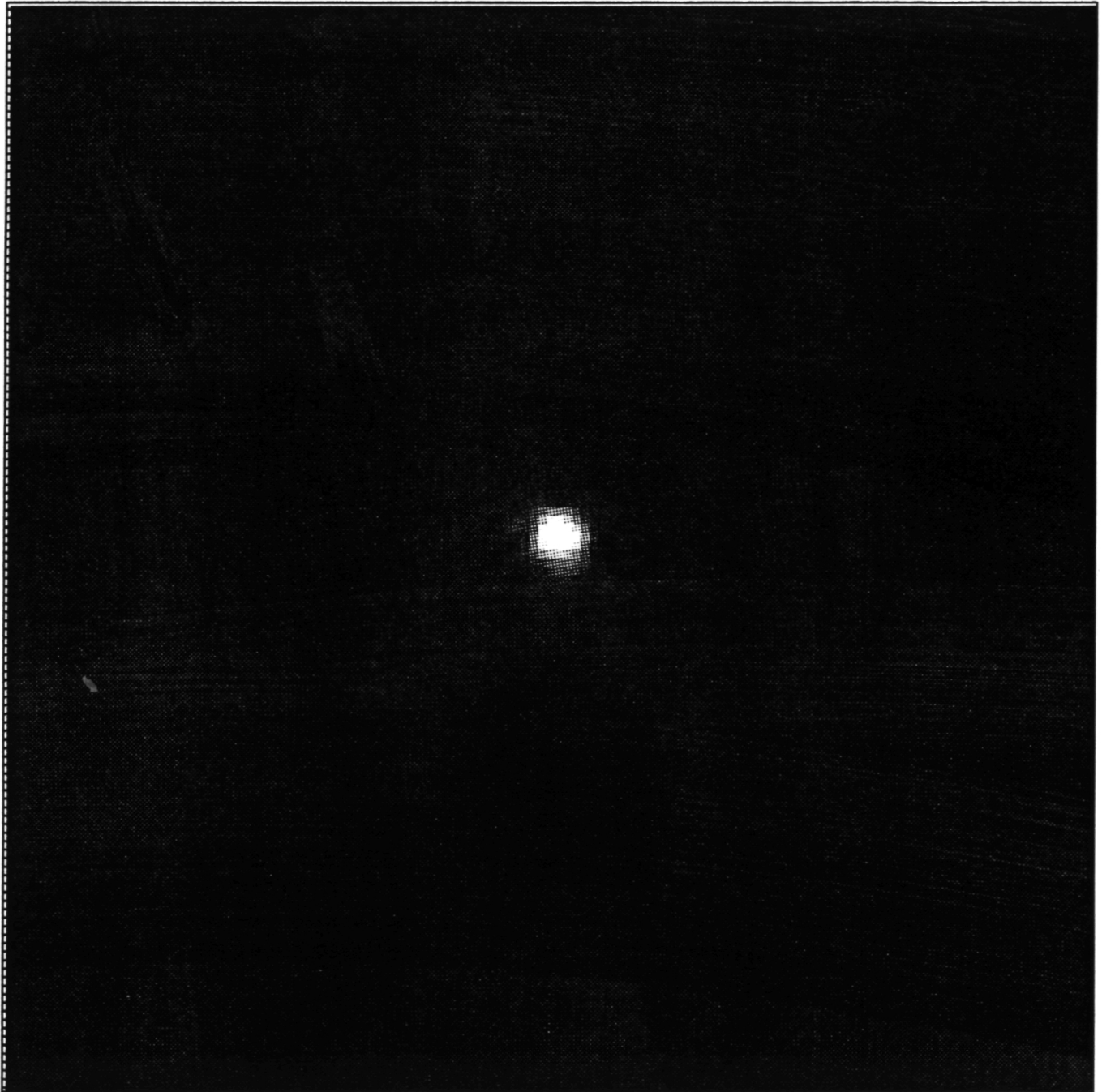


Figure (2) - BID Deconvolution for Cyg X-1

dem71gzm

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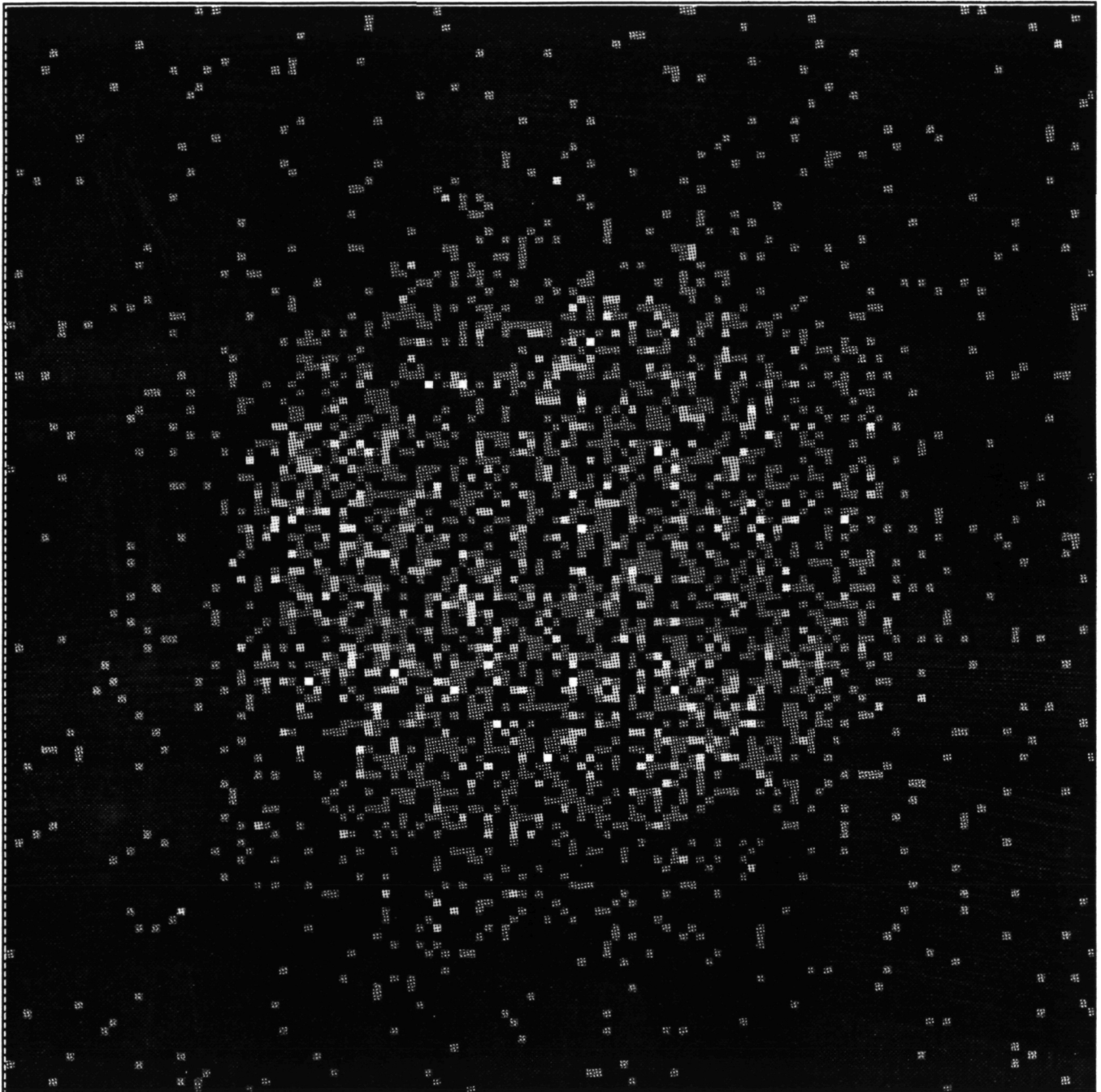


Figure (3) - Einstein data for DEM71

dem71d100w4

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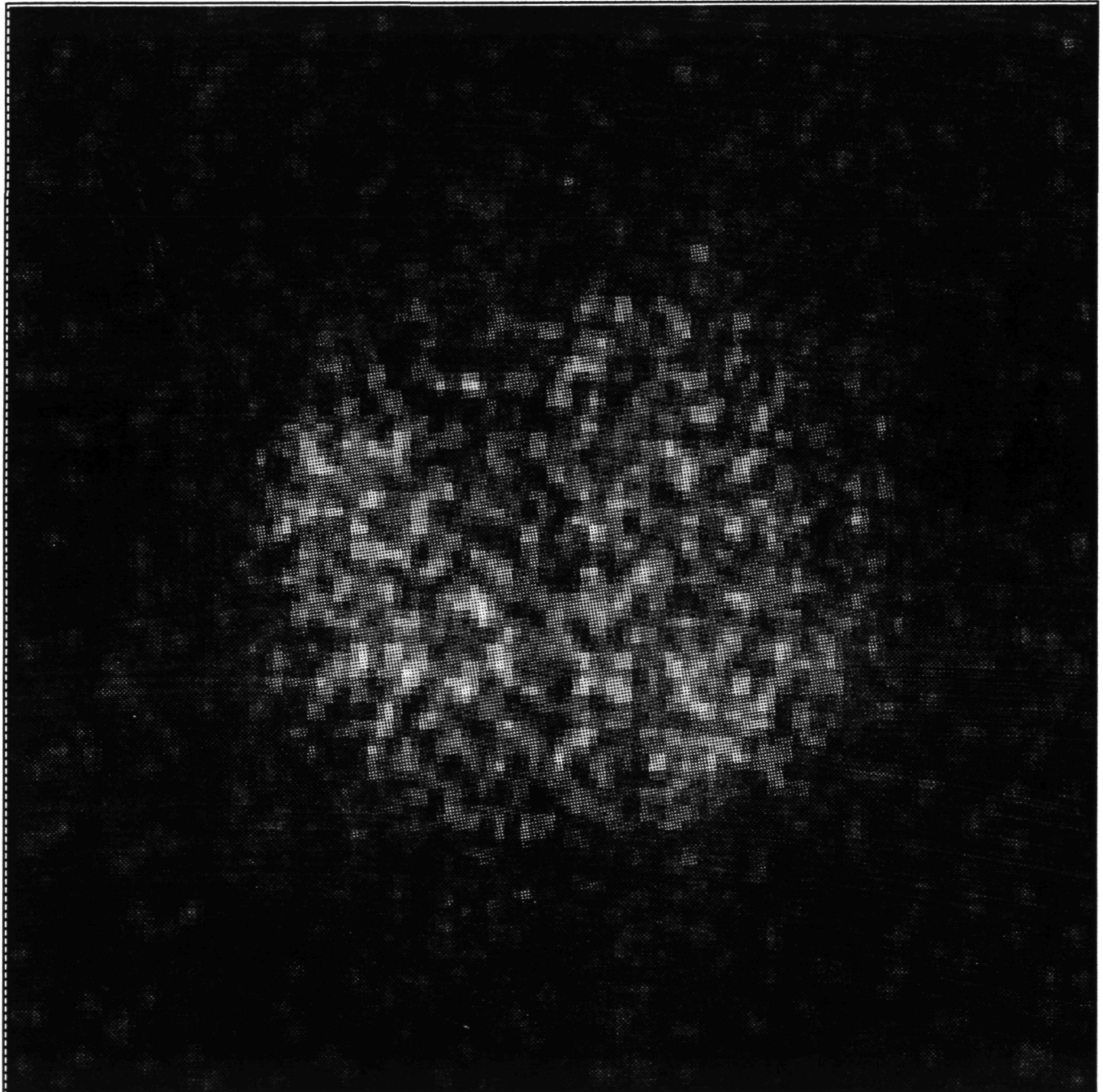


Figure (4) - Bid Deconvolution for DEM71

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n23gzm



Figure (5) - Einstein Data for N23

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n23d100w4

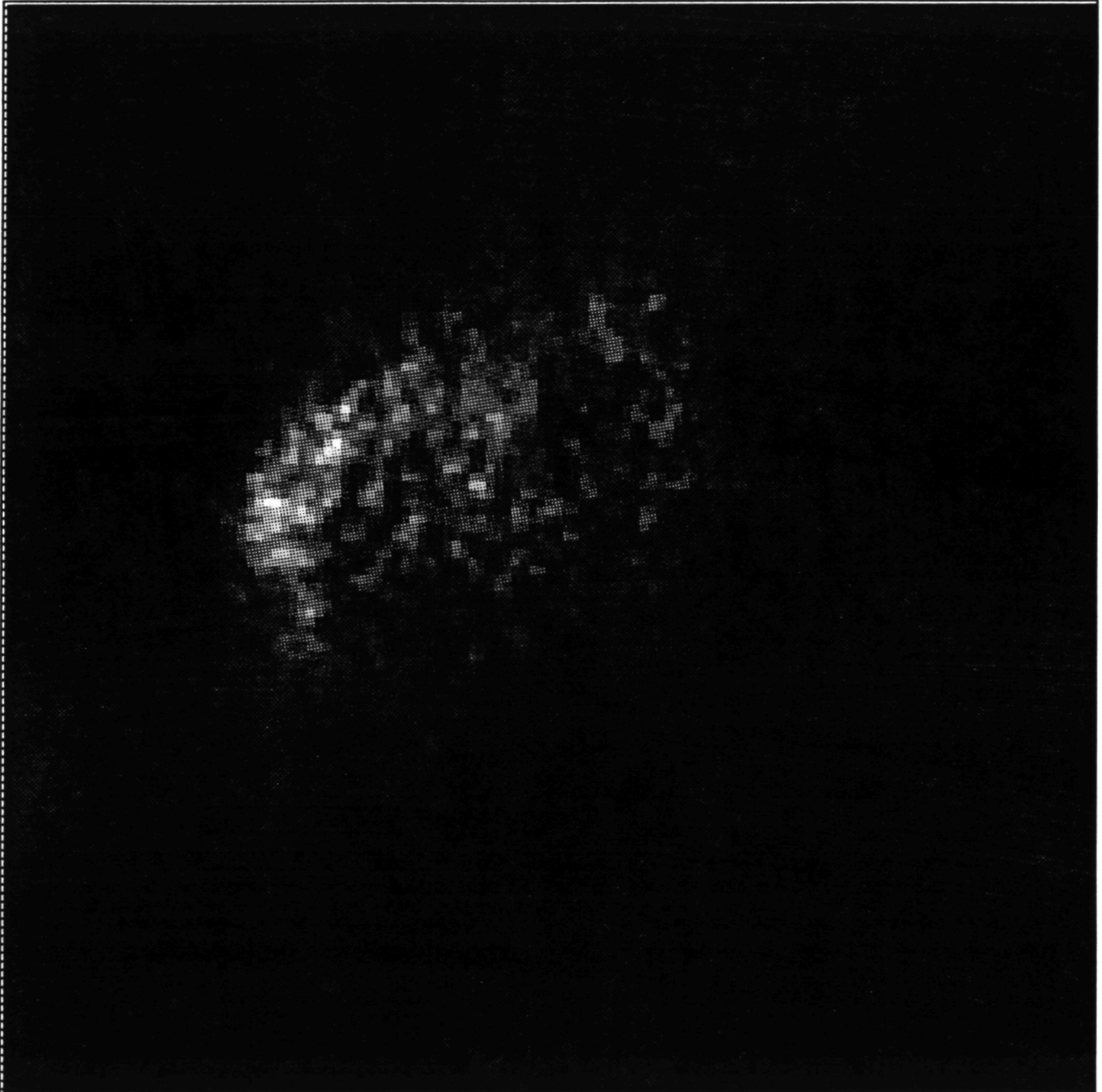


Figure (6) - BID Deconvolution for N23

n49gzm

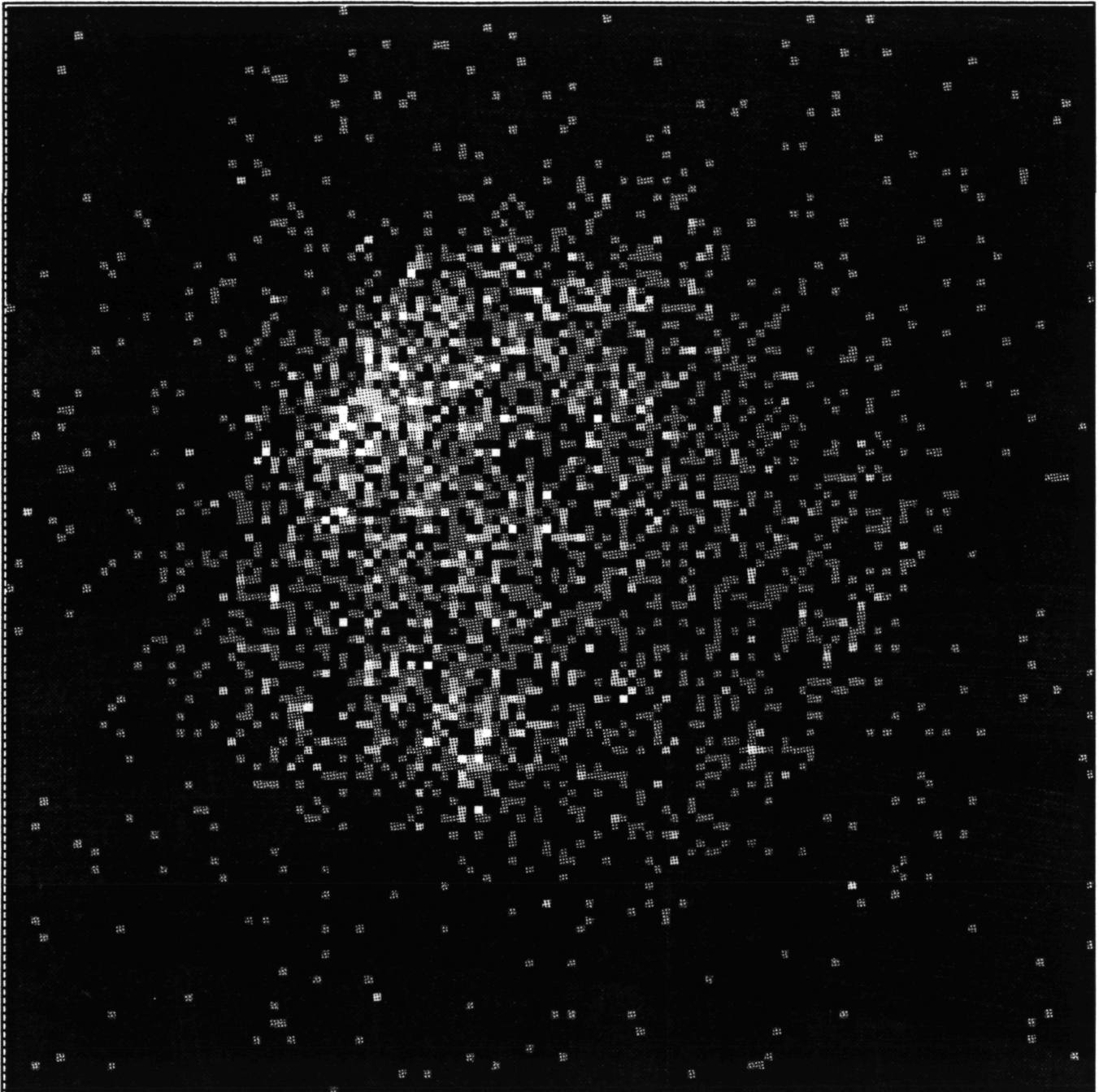


Figure (7) - Einstein data for N49

n49d100w4

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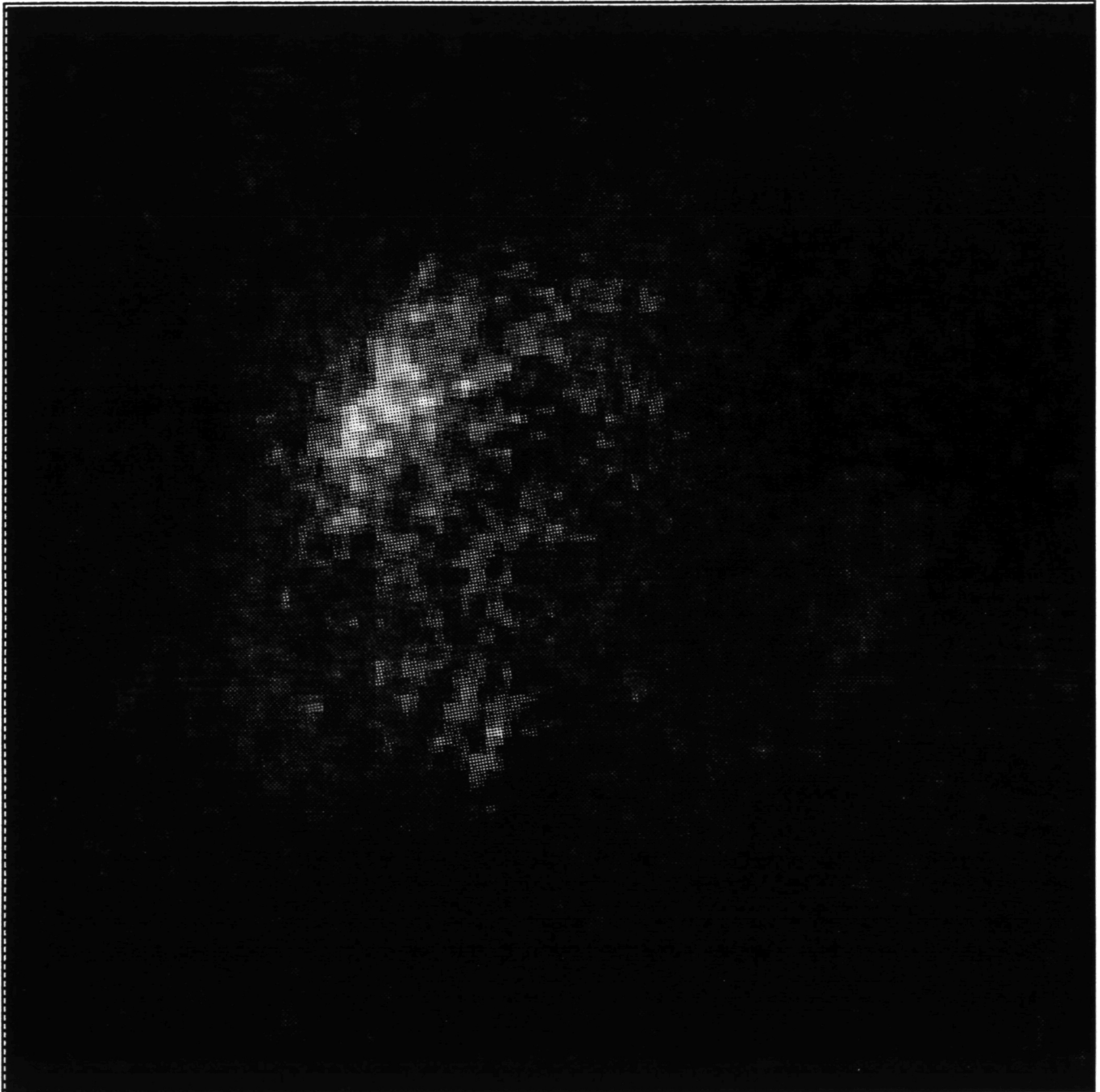


Figure (8) - Bid Deconvolution for N49

n49bgzm

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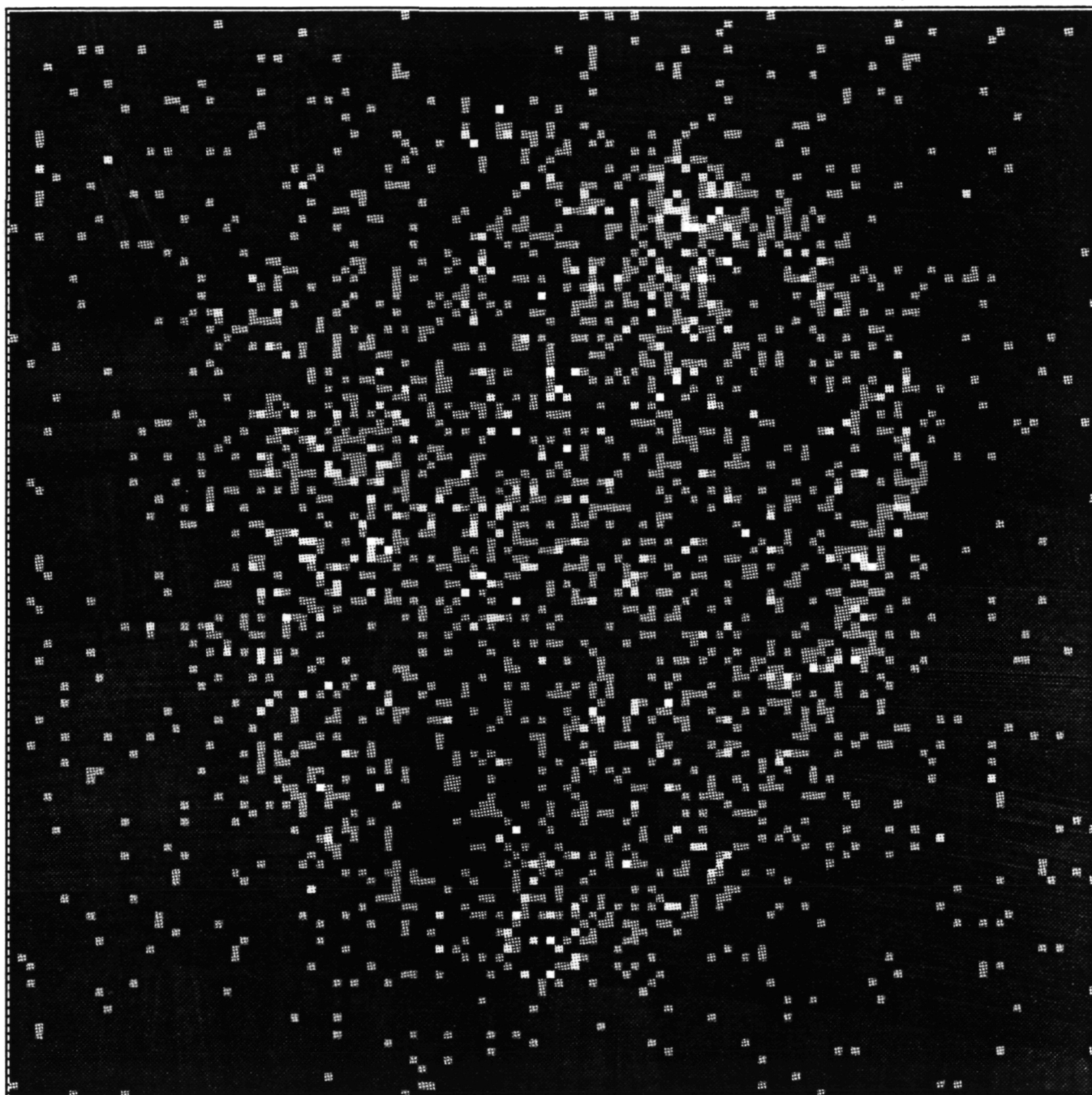


Figure (9) - Einstein Data for N49B

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n49bd100w4

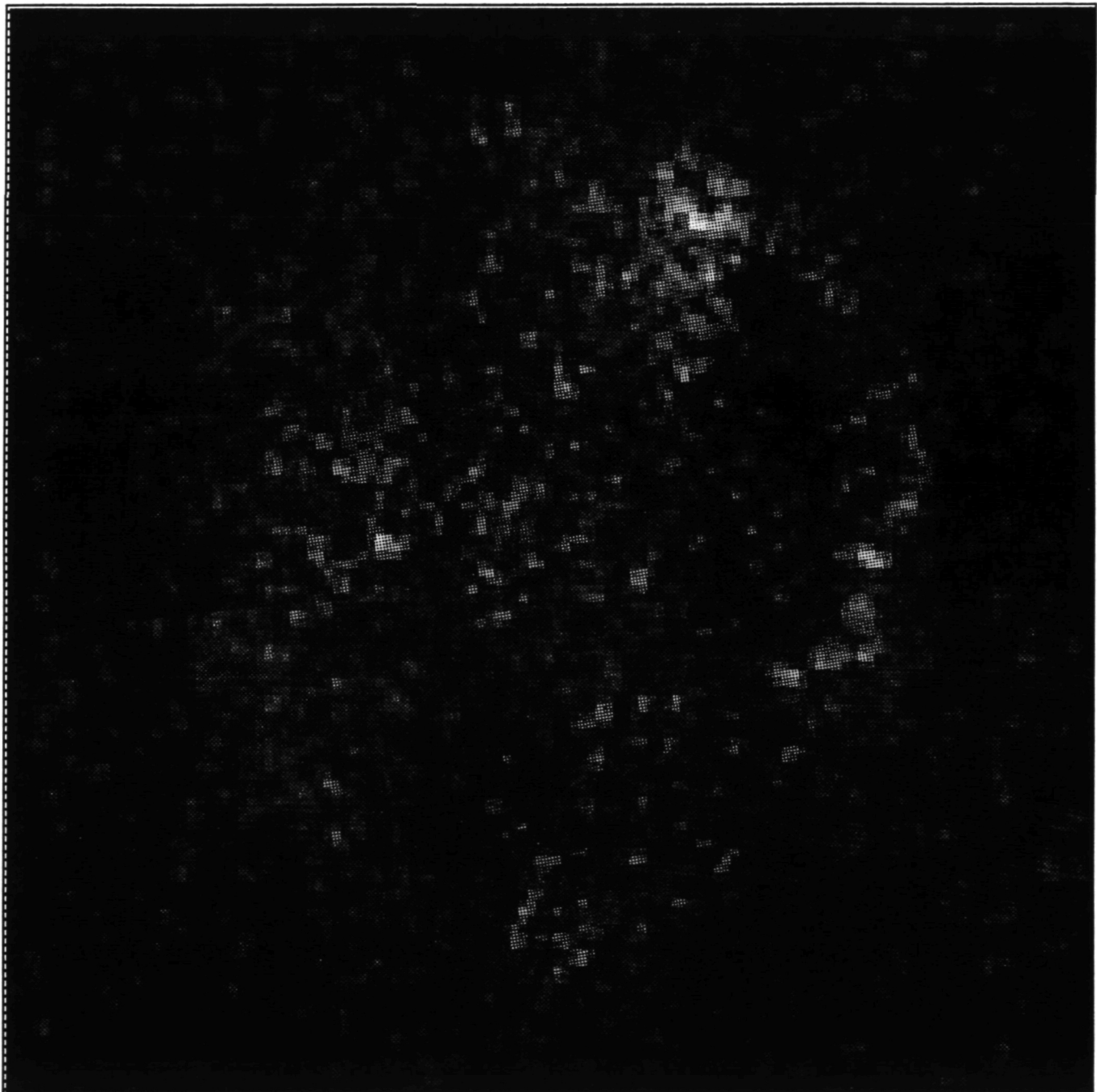


Figure (10) - BID Deconvolution for N49B

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n63agzm

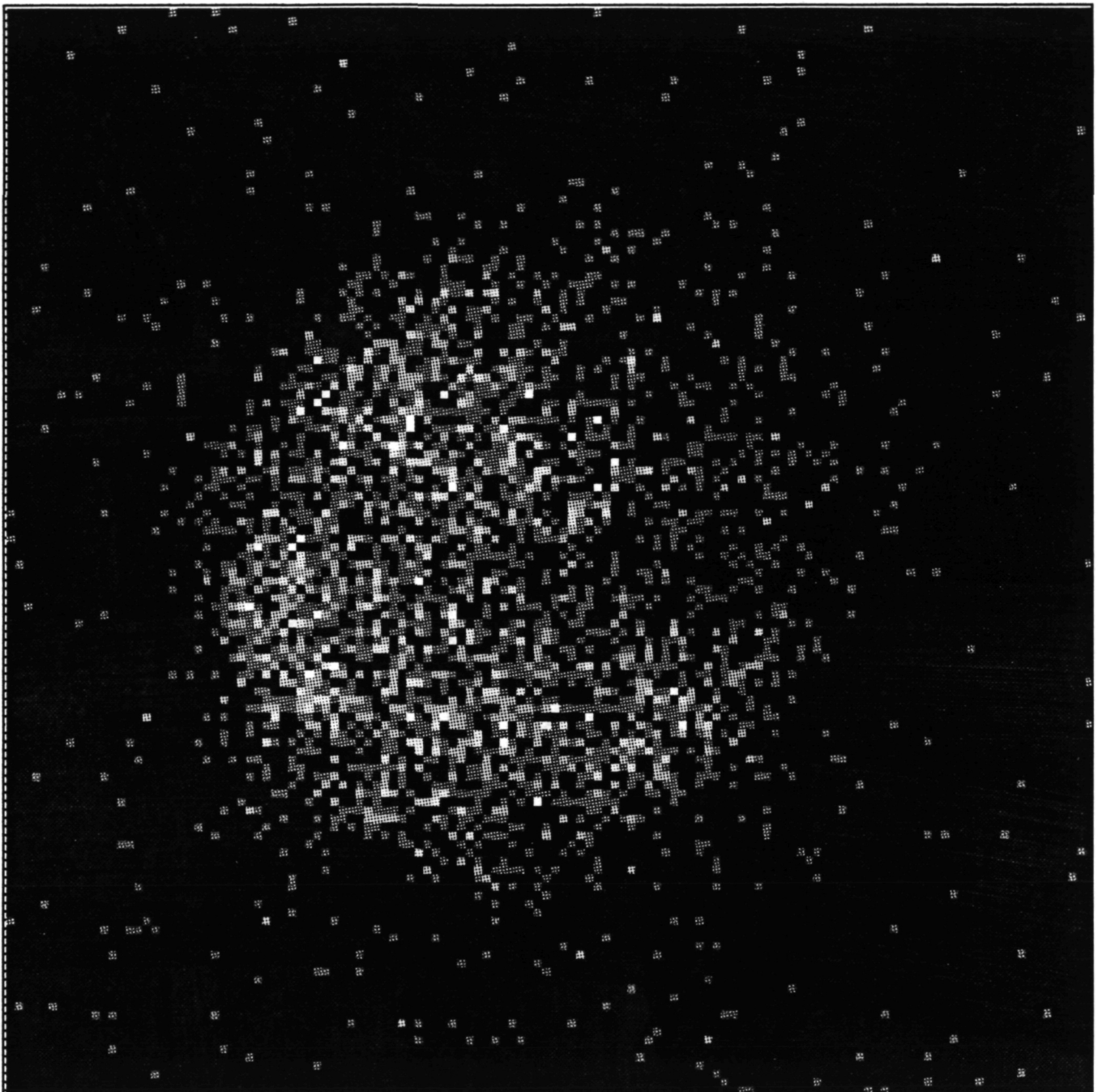


Figure (11) - Einstein data for N63A

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n63ad100w4

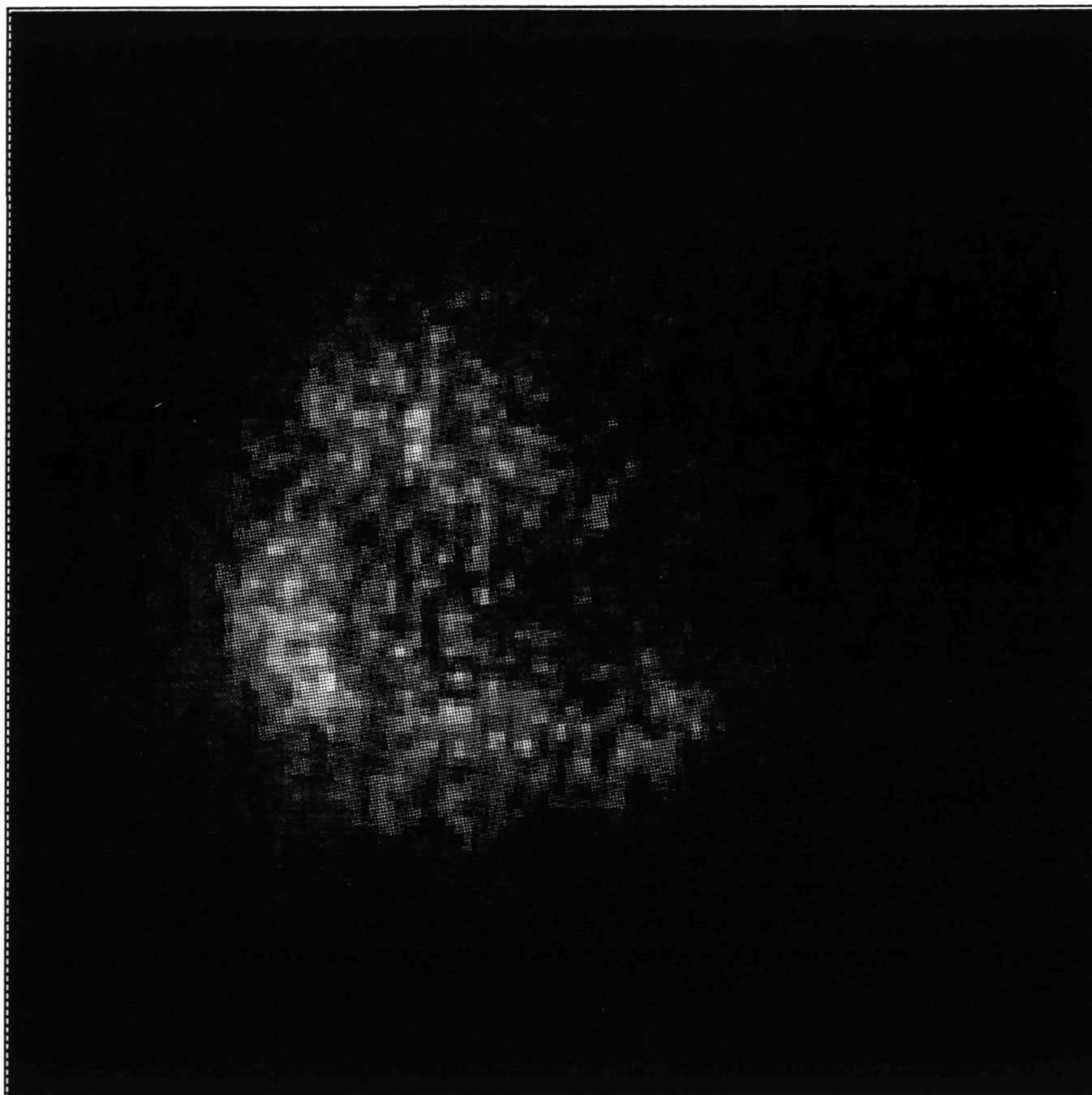


Figure (12) - Bid Deconvolution for N63A

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n132dgzm

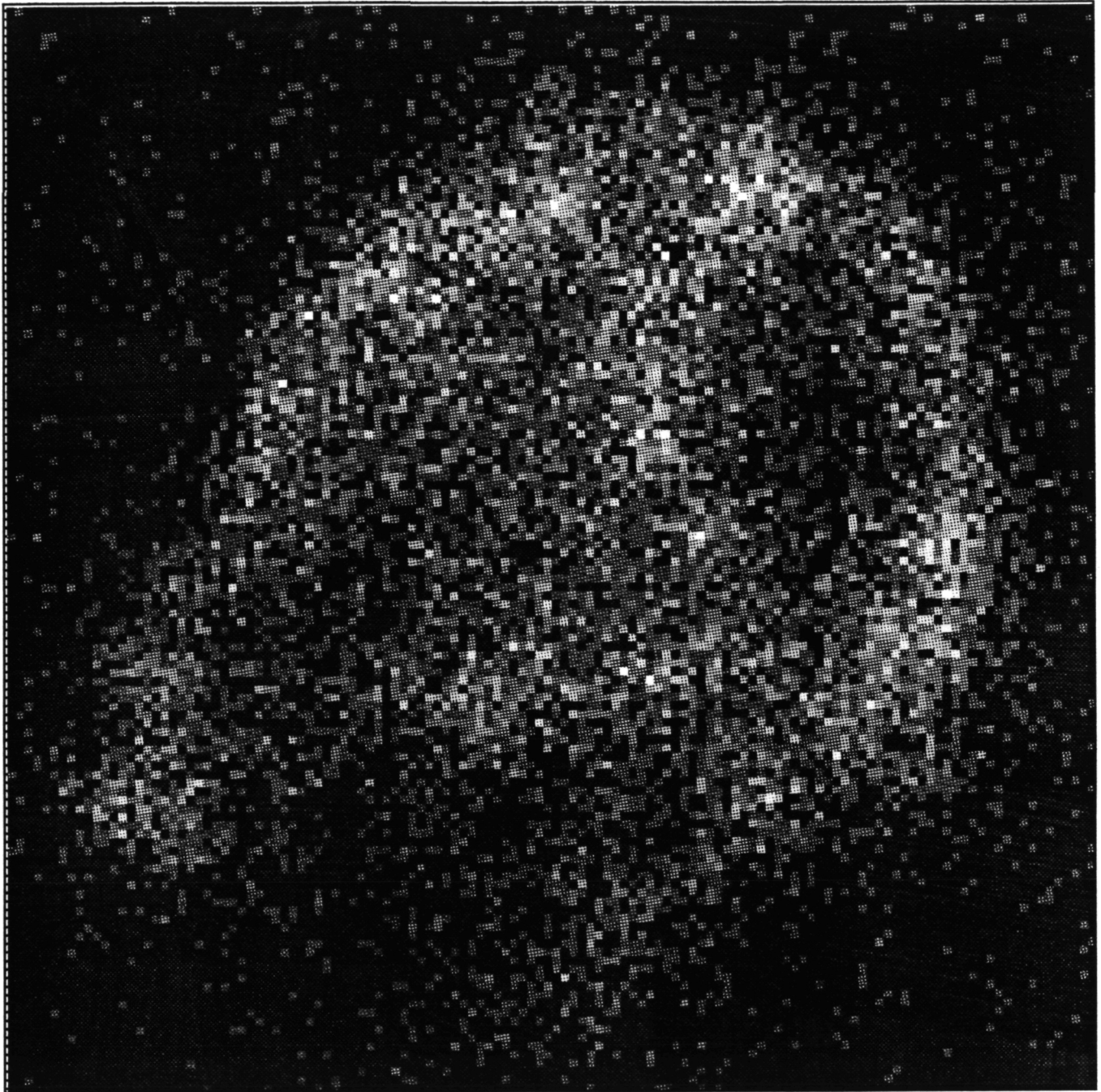


Figure (13) - Einstein data for N103B

n132d100w4

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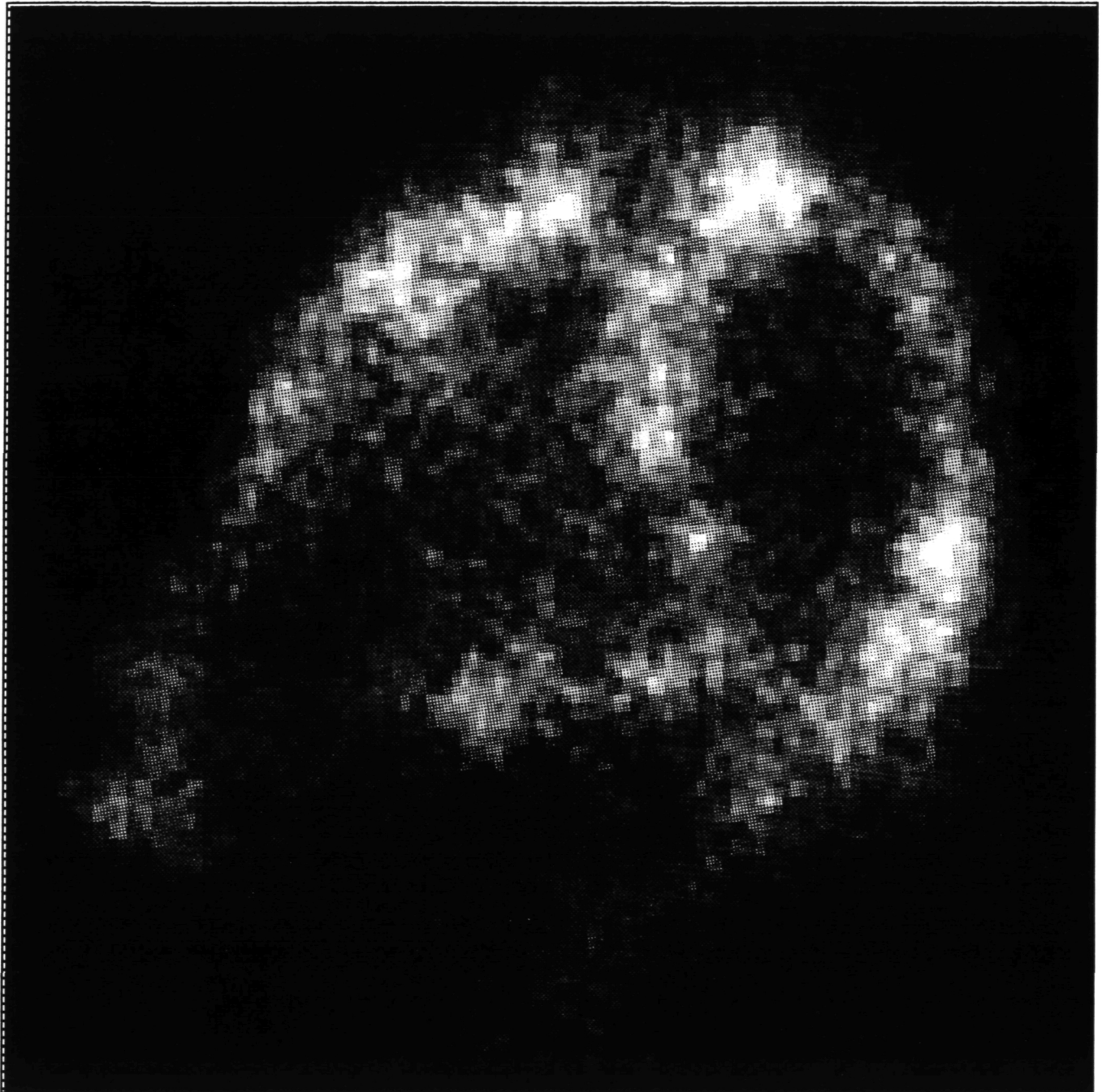


Figure (14) - Bid Deconvolution for N103B

n103bgzm

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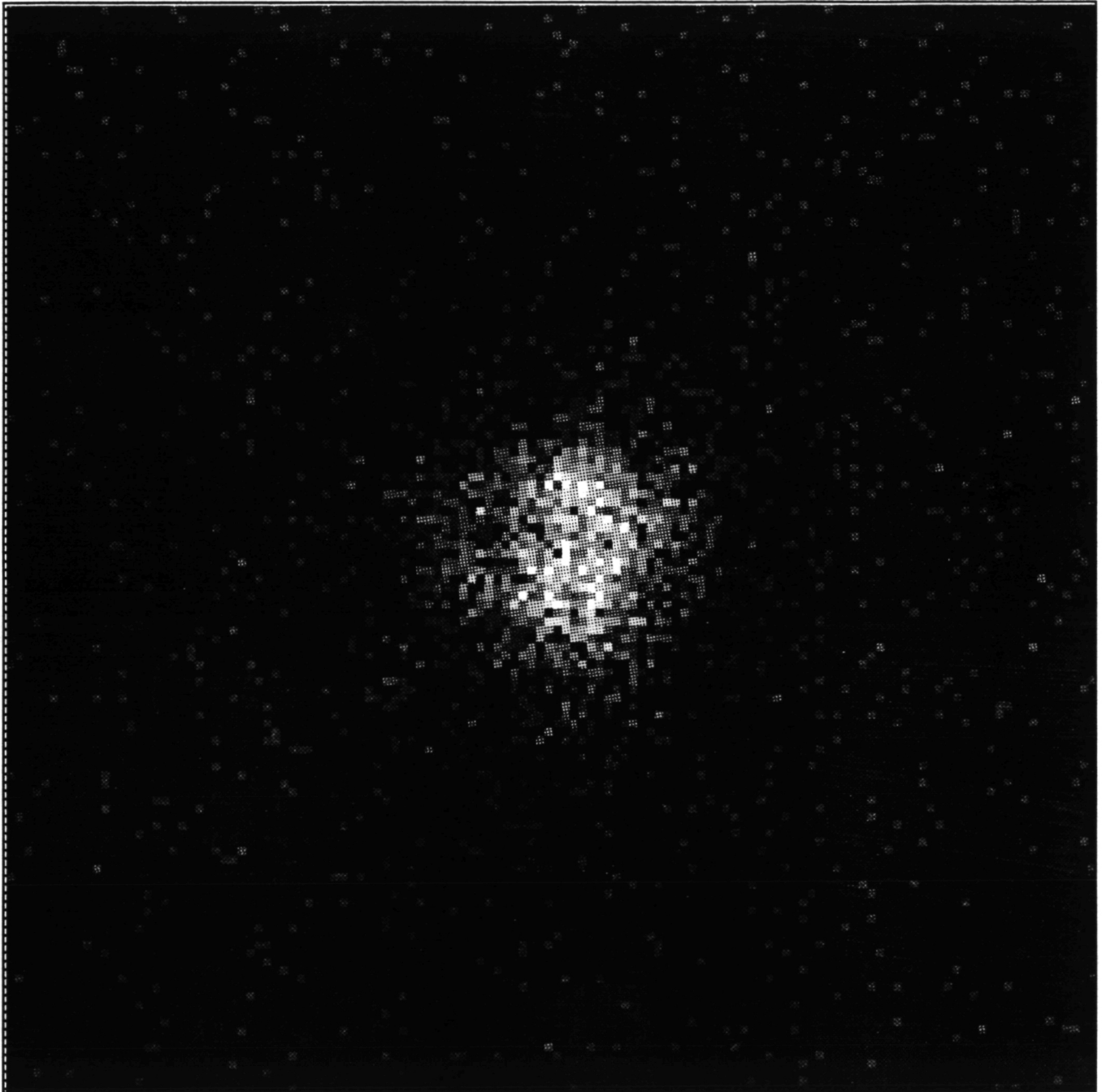


Figure (15) - Einstein Data for N132D

n103bd100w4

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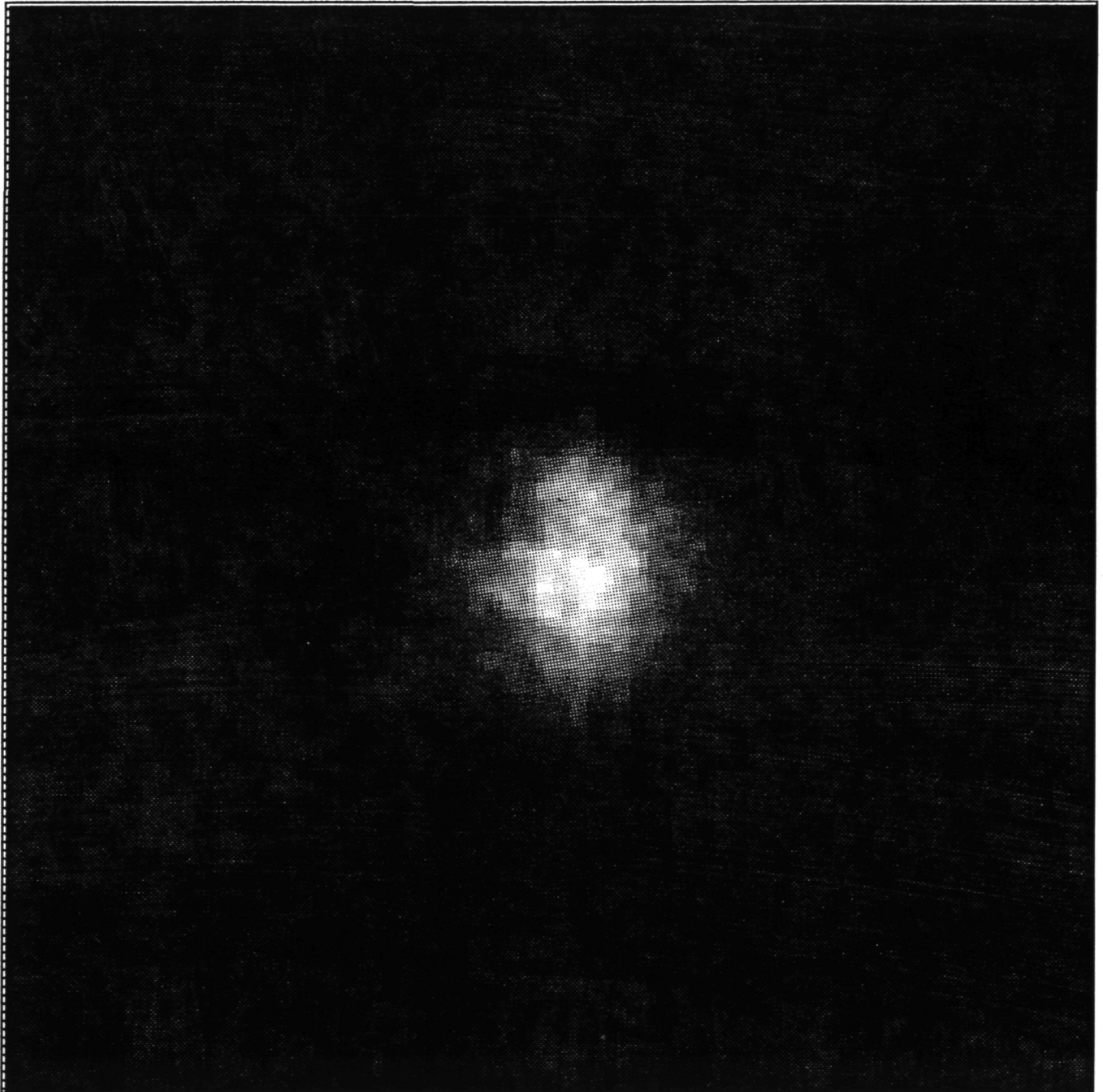


Figure (16) - BID Deconvolution for N132D

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snr0102gzm

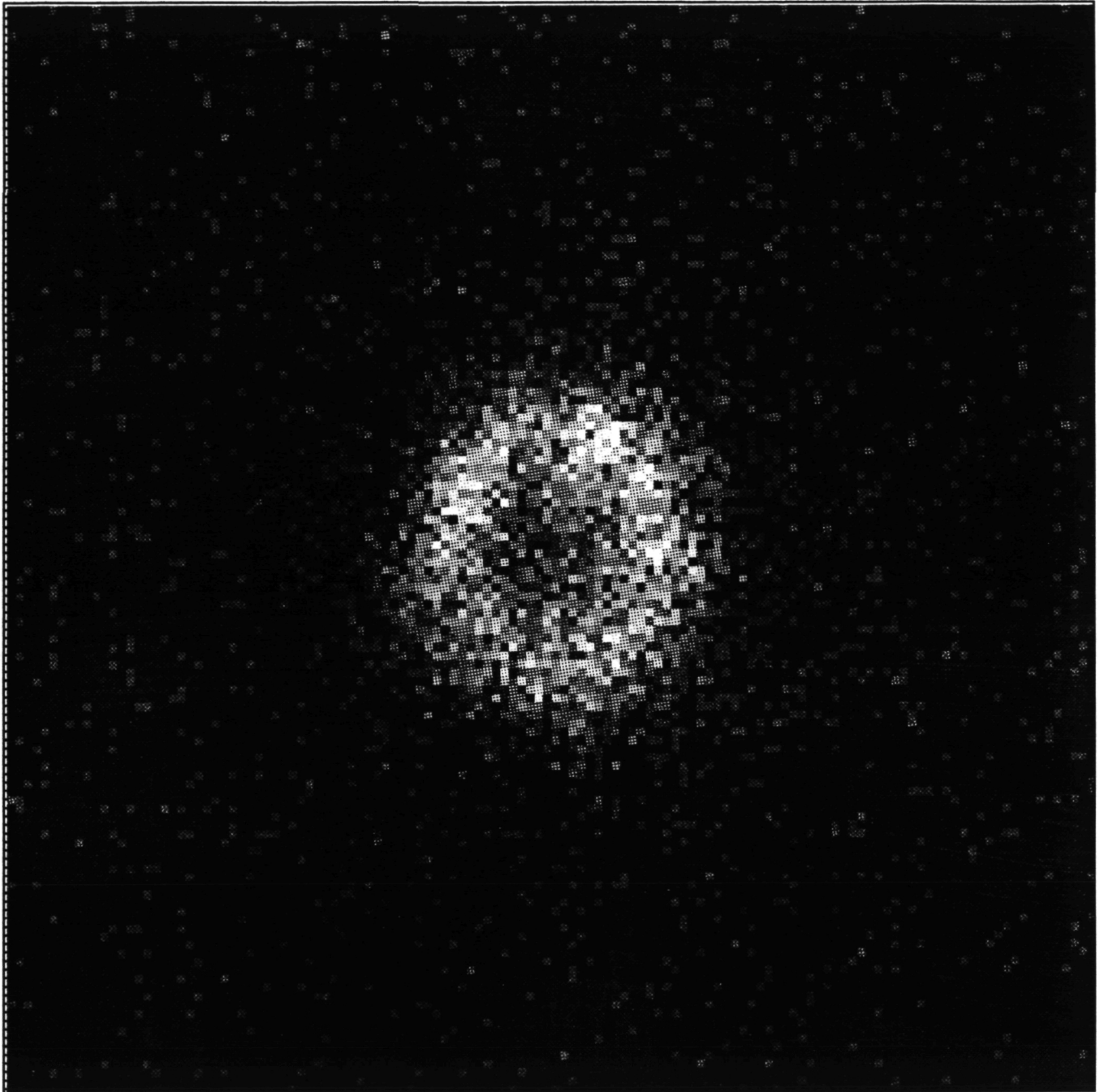


Figure (17) - Einstein Data for SNR0102

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snr0102d100w4

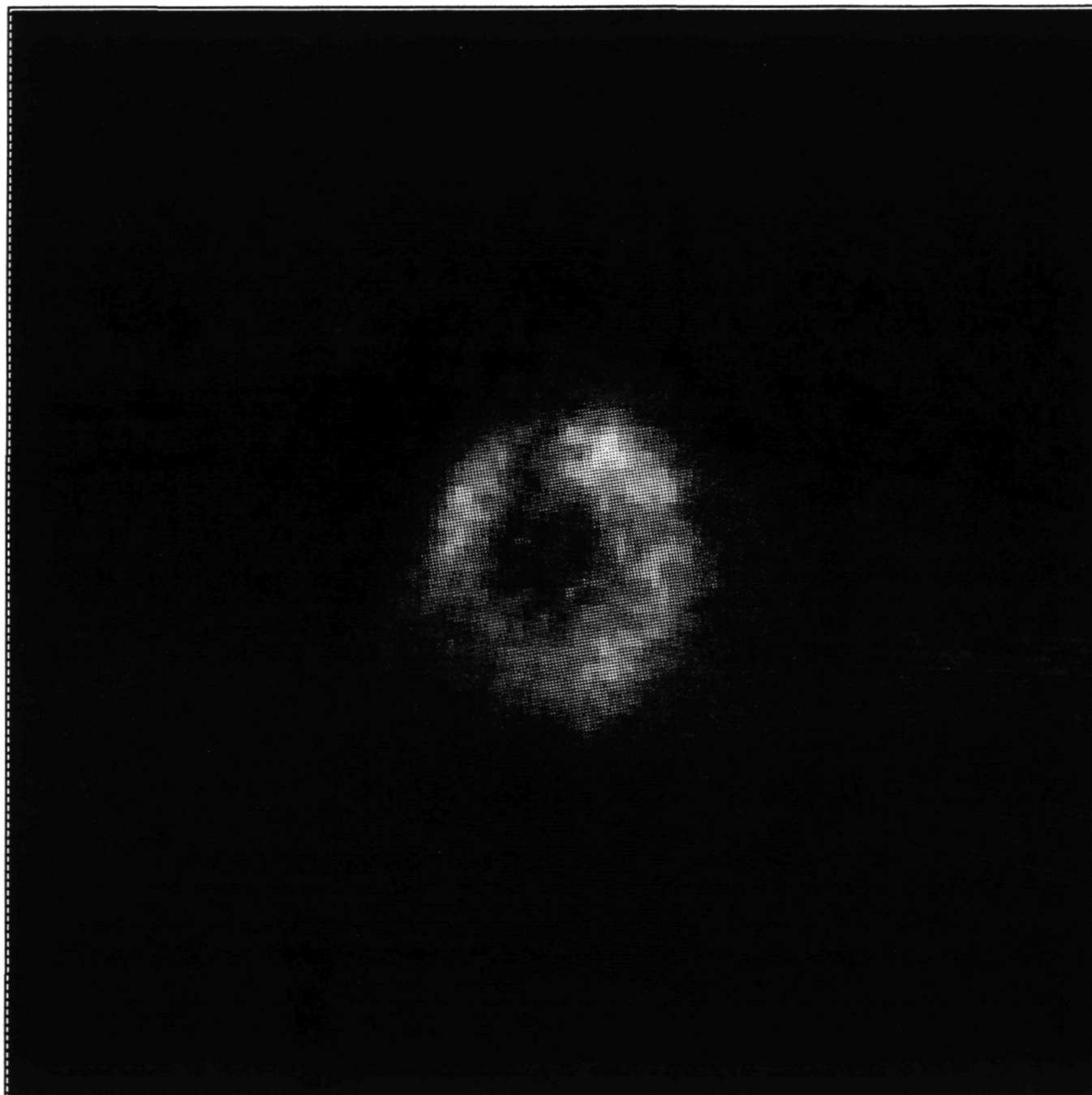


Figure (18) - BID Deconvolution for SNR0102

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snr0519gzm

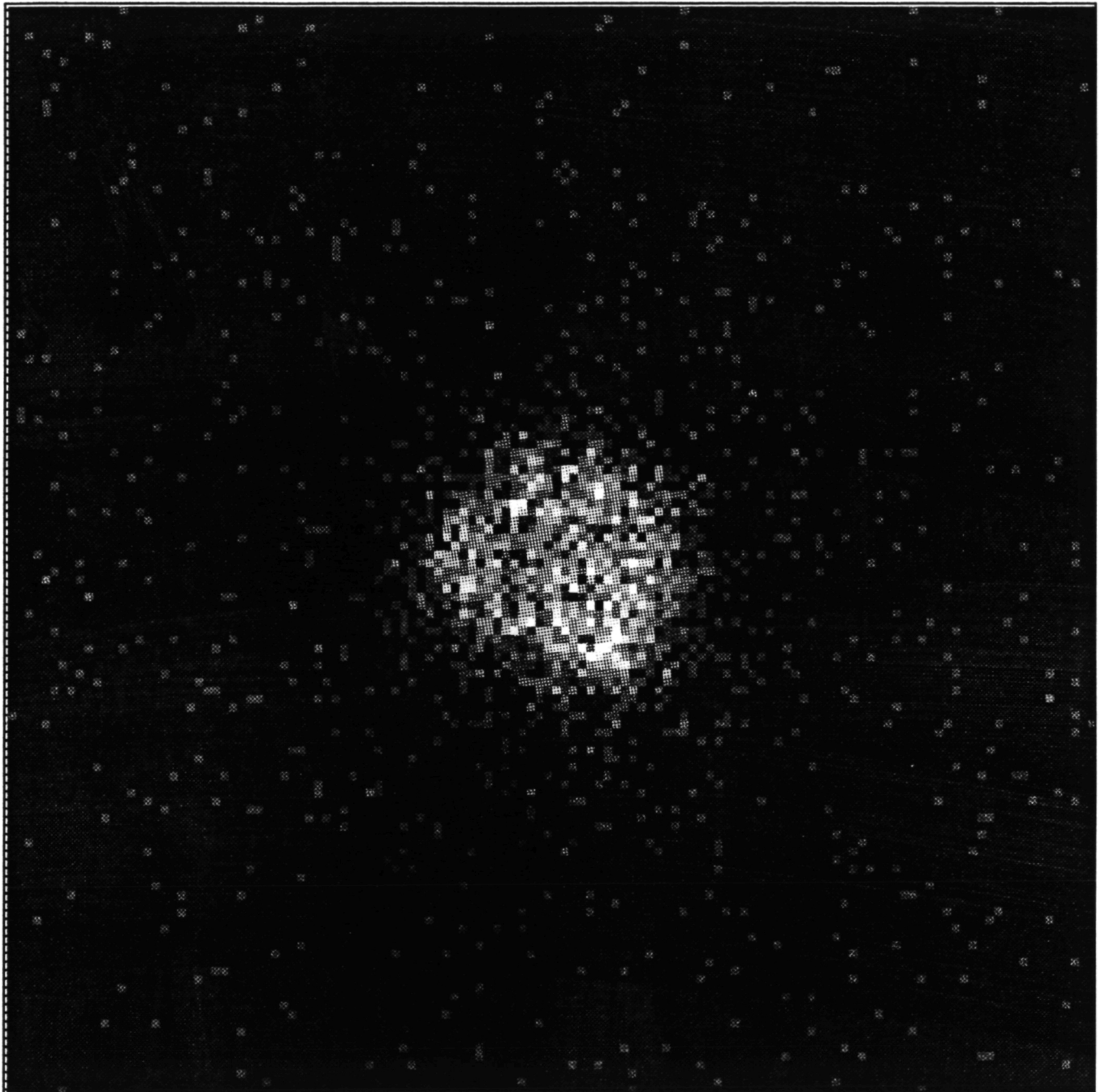


Figure (19) - Einstein data for SNR0519

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snr0519d100w4

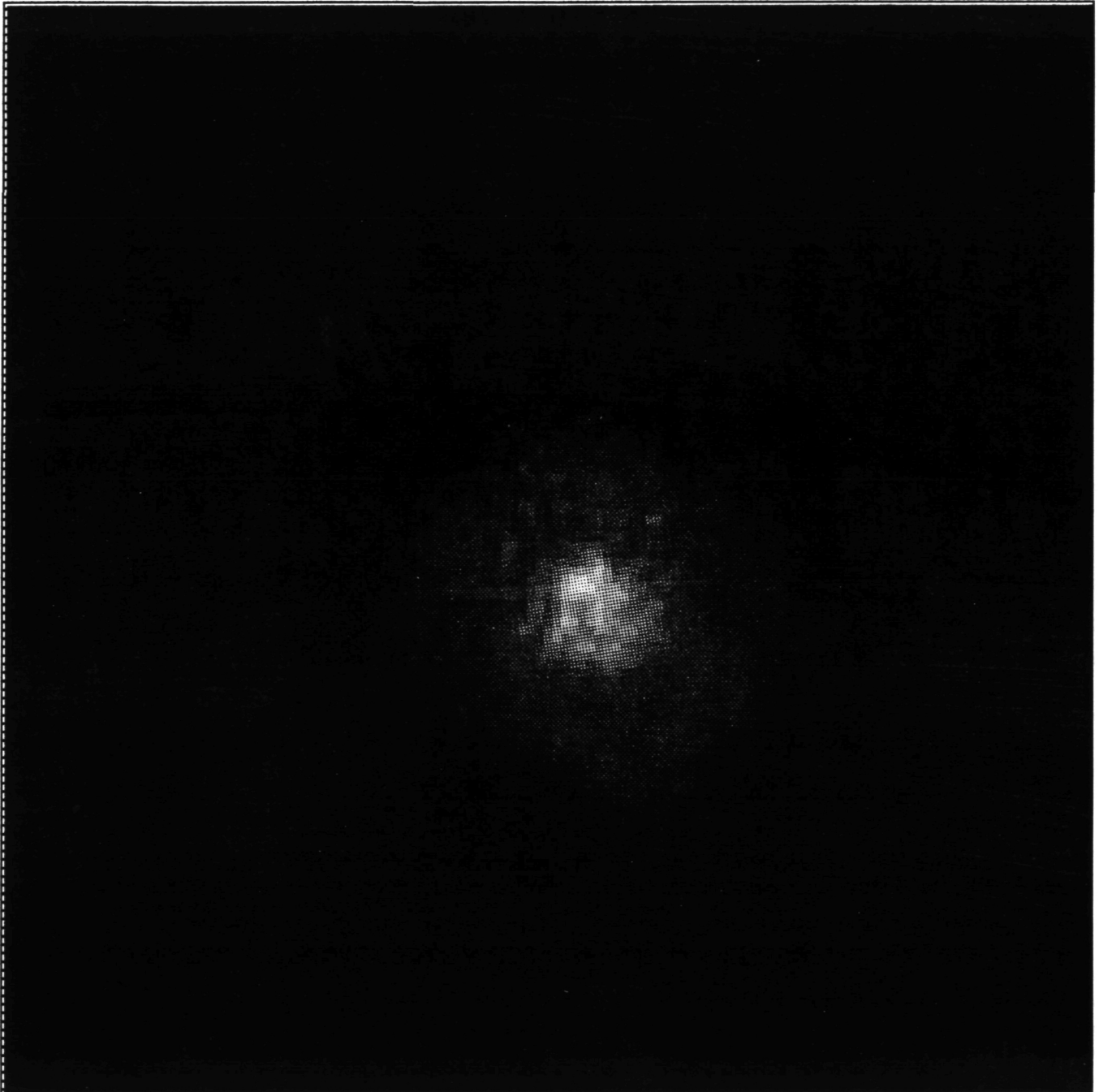


Figure (20) - Bid Deconvolution for SNR0519

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snr0540Hgzm

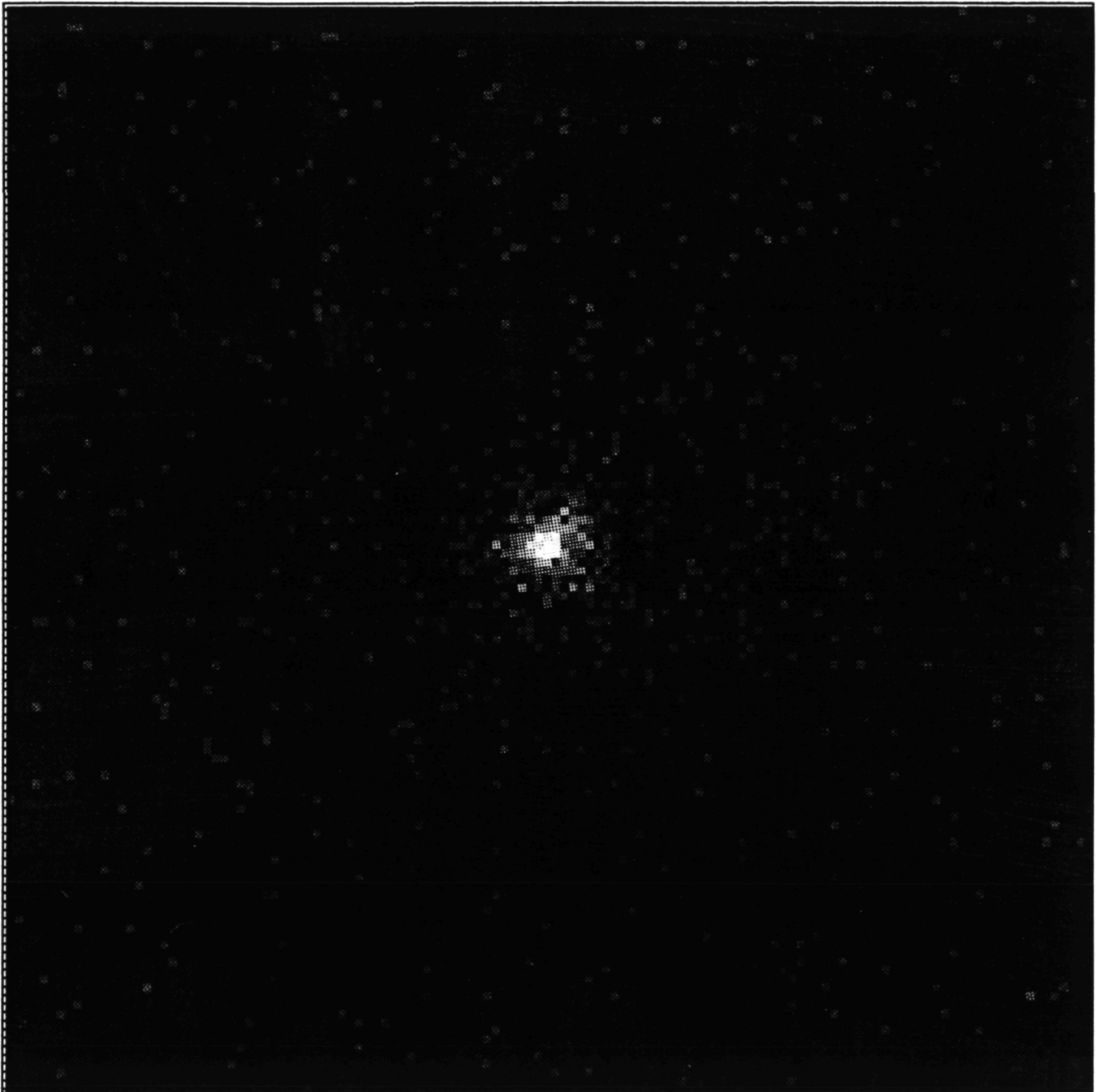


Figure (21) - Einstein Data for SNR0540

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snr0540Hd100w4

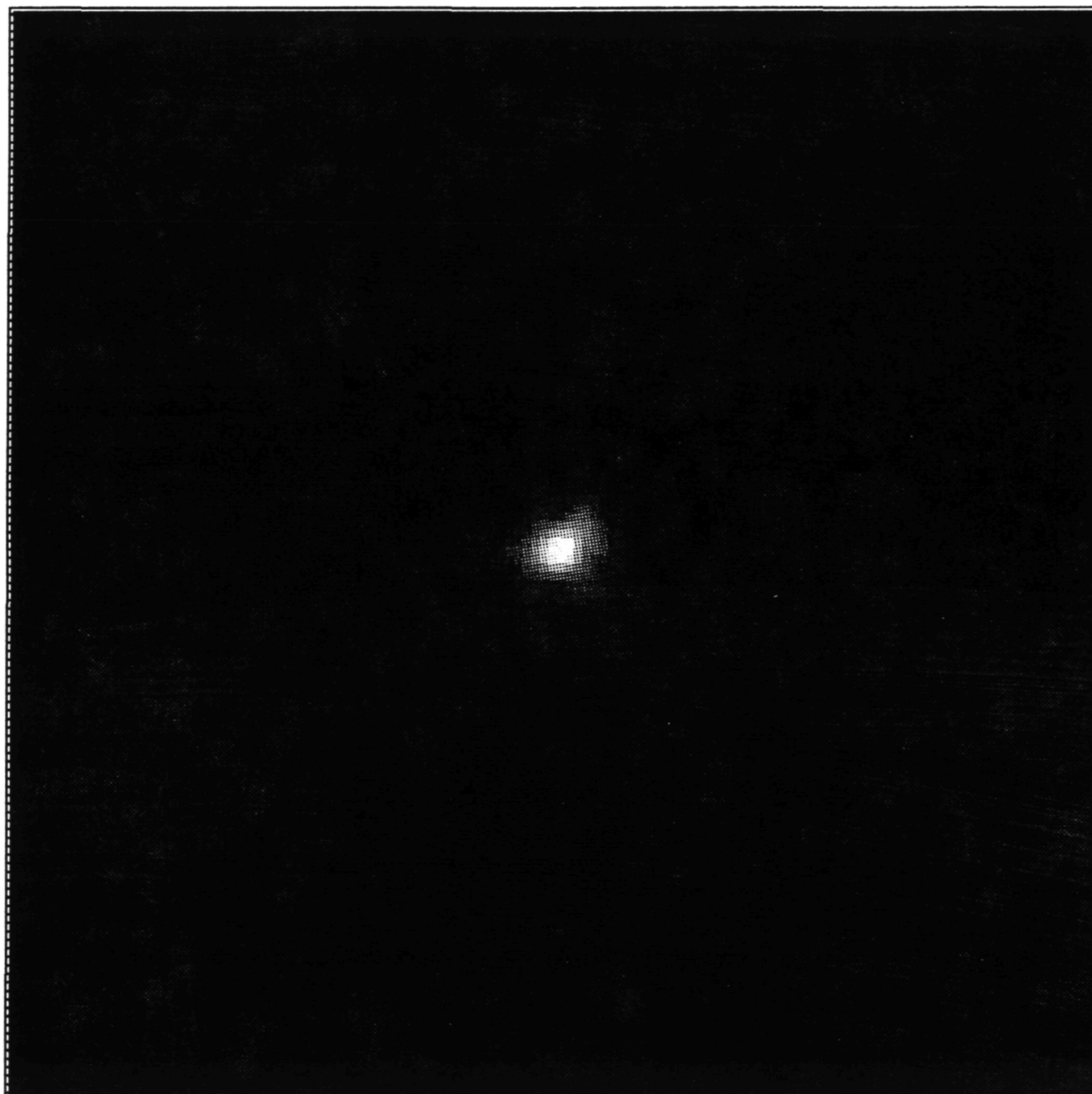
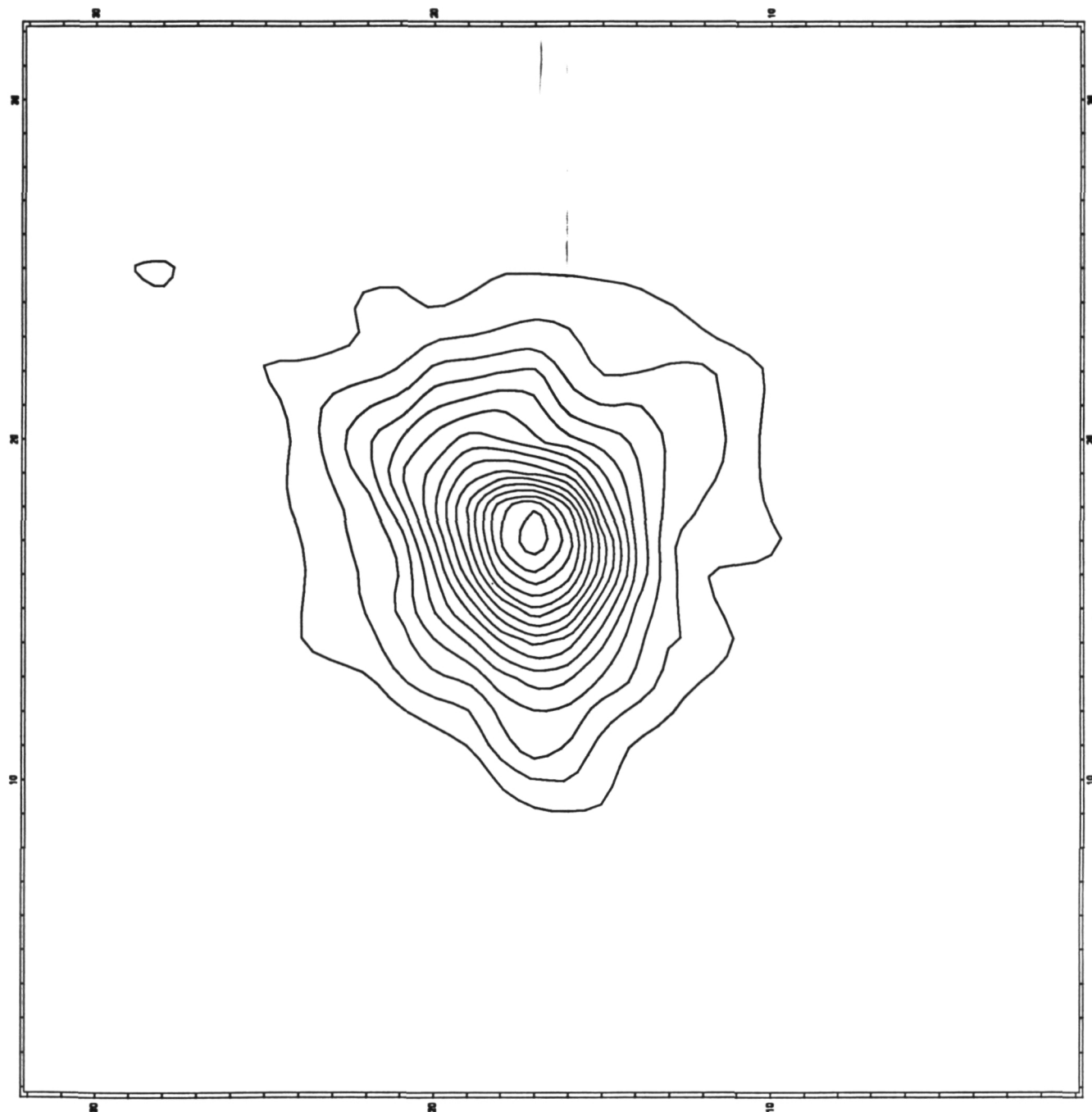


Figure (22) - BID Deconvolution for SNR0540

snr0540d100w4[49:80,49:80]:



contoured from 0. to 9.6, Interval = 0.6
NOAO/IRAF V2.9.1EXPORT nlsnson@cfasp36.harvard.edu Wed 09:34:46 15-Jan-92

Figure (23) - Contour Plot of the BID Deconvolution of SNR0540

snr0540d100w4:

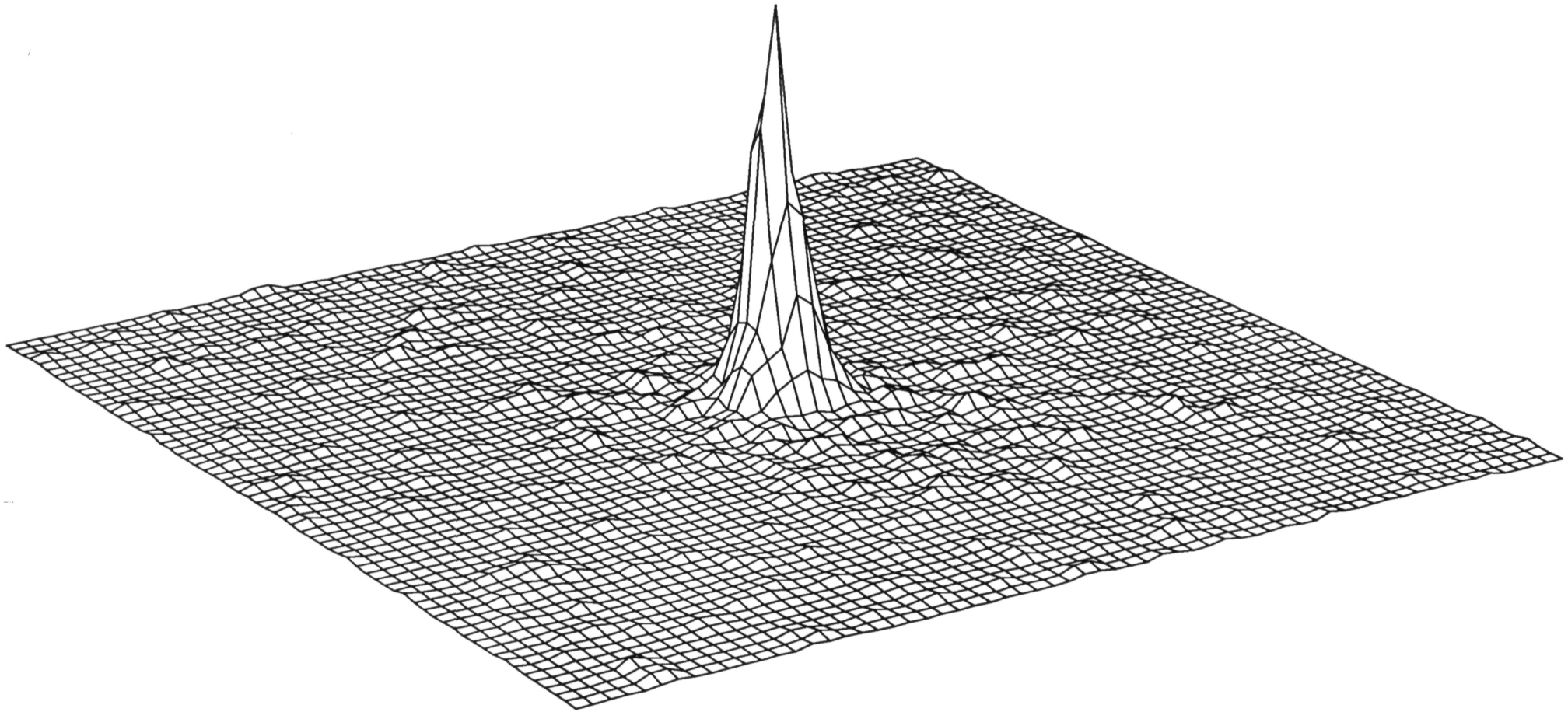


Figure (24) - Surface Plot of the BID Deconvolution of SNR0540

Appendix A

program bid

```
c last edited: January 6, 1992
c Compile in IRAF using FC
c link with bidsb, irafsb, and fourt
c perform blind iterative deconvolution
c using wiener filters only
c needs input image, guess at psf
c
c*****
c BID is set up to take square IRAF image arrays of up to 512x512
c Smaller arrays or smaller processing areas are chosen by
c entering the parameter KSZ.
c Images smaller than KSZ are set in KSZ arrays and the outer
c regions are filled with either zero or an average constant.
c Images larger than KSZ (but smaller than 513x513) are
c chunked to KSZ area, at an entered center.
c File names are for IRAF files without the .imh.
c 1st guess psf can be either a file or it can be generated with
c PSFGEN.
c Program runs for MAXC cycles.
c BETA is the percentage (0 to 1.0) of the previous cycle averaged
c with the current cycle. Usually 0.8 near the start of the
c process, but changed to 1.0 near convergence.
c Resulting psf's and images can be read back into the program
c to perform additional cycles.
c CF is the radius in frequency space used for the Wiener filter
c noise estimate. 1.0 is a good starting point.
c W1 is the Wiener filter scale factor. 1.0 is a good starting
c value. Program DCW allows generation of Wiener filtered
c versions of the image using the psf from BID, but with different
c values for W1. Larger values for W1 give a smoother image,
c smaller values enhance the high frequencies.
c Output file names should be given without the trailing .imh.
c Object and psf masks are generated using program MAKEMASK.
c Recommended starting masks should be of order twice the diameter
c of the data and expected psf diameters. For an object that nearly
c fills the field, a constant mask (equivalent to no mask) should
c be used for the object and only a psf mask is used.
c
c If you encounter problems in using this program, contact
c Peter Nisenson, Center for Astrophysics, (617) 495-7394
c
```

```
parameter (isz=512, isz1=isz/2, isz2=isz1+1)
```

```
c complex fourier space arrays : c = g*f
      complex  c(isz*isz)
      complex  g(isz*isz)
      complex  f(isz*isz)

c real image space arrays, 1-d here but all routines think they are 2-d
      real  cobj(isz*isz), gref(isz*isz), fout(isz*isz), lastfout(isz*isz)
c masks and a temporary buffer
      real  maskr(isz*isz), mask(isz*isz), tempb(isz*isz)
c total power of input image
      real  power
c two working arrays, one for fourt, one for loadim
      real  work(2*isz), rwk(isz)
c test, testr, rmsdiff array, for output to file
      real  stats(isz,3)

c temp integer array for loadim :
      integer  iph(isz,isz)
```

```

c nzero and nzeror are number of non-zeros (ones) in mask and maskr :
    integer          nzero,nzeror
c parameters for fourt :
    integer*4        nn(2),ndim,isign,iform
c file names :
    character         name1*80,name2*80,name3*80,name4*80,name5*80

    print *, ' BID : iterative deconvolution given initial '
    print *, ' guess at the psf, uses wiener deconvolution, '
    print *, ' support and positivity constraints to iteratively'
    print *, ' approximate the correct psf ...'
    print *, ''

    print *, ' Enter log file name'
    read (*,*) name5
    open(unit=1,name=name5,type='new',form='formatted')

c initialize ...
    print *, ' enter array dimension (ksz) '
    read (*,*) ksz
    write (1,*) ' array dimension ',ksz
    ksz1=ksz/2
    ksz2=ksz*ksz
    nn(1)=ksz
    nn(2)=ksz
    ndim=2

c
c read in image file, save total power for rescaling output
c
    print *, ' enter input image file name '
    read (*, '(a)') name1
    write (1,*) ' Input file name',name1
    call loadim (name1,cobj,iph,rwk,ksz,3)

    print *, ' 1 for border square mask, 2 for circular, 0 for none'
    read (*,*) isqm
    if (isqm.eq.1)then
        print *, 'Enter the sqmask border width, 0 for none'
        read (*,*) iradm
    elseif(isqm.eq.2)then
        print *, ' Enter circular mask radius '
        read (*,*) radm
    endif

c apply square gaussian border
    if (isqm.eq.1)call sqmask(cobj,iradm,ksz)

c apply circular gaussian border
    if (isqm.eq.2)call circmask(cobj,radm,ksz)

    power=0.0
    do j=1,ksz2
        power=power+abs(cobj(j))
    enddo
    print *, ' Total power in image:',power
    write (1,*) ' Total power in image ',power

c
c read in the psf file and center it, scale total power to 1.0
c
    print *, '1 to enter psf file, 2 to generate gaussian'
    read(*,*) igss
    if(igss.eq.1)then
        print *, ' enter input psf file name'

```



```

        read (*,'(a)') name1
        write (1,*) 'Input psf file name ',name1
        call loadim(name1,gref,iph,rwk,ksz,3)
        call centre(gref,tempb,ksz,ksz1)
        call scale(gref,1.0,ksz)
    else
c generate 1st pass psf
c
        print *, 'Generate psf'
        print *, ' Enter 1/e radius for psf '
        read (*,*) wid
        write (1,*) ' Gaussian psf 1/e radius ',wid
        krn=1
        cf=1.0*ksz1
        call gauss(gref,wid,krn,ksz)
        iform=0
        isign=-1

        call copyr(g,gref,isign,ksz)
        call fourt(g,nn,ndim,isign,iform,work)

        call rolloff(g,cf,ksz)
        iform=1
        isign=1
        call fourt(g,nn,ndim,isign,iform,work)
        call copyr(g,gref,isign,ksz)
        call fmax(amax,amin,imax,jmax,imin,jmin,gref,ksz)
        amm=amax-amin
        do j=1,ksz2
            gref(j)=(gref(j)-amin)/amm
        enddo
    endif
c
c enter reconstruction parameters
c
        print *, ' enter max # cycles for iteration '
        read (*,*) maxc
        write (1,*) ' max # iterations ',maxc

        print *, ' enter beta, the damping factor (try 0.8)'
        read (*,*) beta
        write (1,*) ' beta ',beta

        print *, ' enter radius for noise estimate (0 to 1.0)'
        read (*,*) cf
        write (1,*) ' noise radius ',cf
        cf = cf*ksz1
        icf = cf

        print *, ' enter object wiener filter parameter (Try 1.0)'
        read (*,*) wol
        write (1,*) ' object Wiener filter multiplier ',wol

        print *, ' enter psf wiener filter parameter (Try 1.0)'
        read (*,*) wpl
        write (1,*) ' psf Wiener filter multiplier ',wpl

        print *, '1 for circular object support, 2 for threshold,
+ 3 for none'
        read (*,*) ispp

        suppo=0.
        thresh=0.0

```

```

if (ispp.eq.1)then
  print *, ' enter the object support radius, 0 for none'
  read (*,*) suppo
  write (1,*) ' object support radius ',suppo
endif
if (ispp.eq.2)then
  print *, ' enter threshold level for support '
  read (*,*) thresh
  write (1,*) ' object support threshold ',thresh
endif

print *, ' 1 for psf positivity, 2 for just support'
read (*,*) ipss

print *, ' Enter the psf circular support radius, 0 for none'
read (*,*) suppr
write (1,*) ' psf support radius ',suppr

print *, ' enter output image file name '
read (*, ' (a)') name2
write (1,*) ' enter output image file name ',name2

print *, ' enter output psf file name '
read (*, ' (a)') name3
write (1,*) ' output psf file name ',name3

print *, ' enter output statistics file name '
read (*, ' (a)') name4
write (1,*) ' Output stat file name ',name4

```

c
c
c

```

print *, ' 1 to enter output image from previous iteration'
read (*,*) iobj
if(iobj.eq.1)then
  print *, ' enter file name'
  read (*, ' (a)') namel
  write (1,*) ' Old image file name ',namel
  call loadim(namel,fout,iph,rwk,ksz,3)
  isign=-1
  iform=0
  call copyr(f,fout,isign,ksz)
  call fourt(f,nn,ndim,isign,iform,work)
  call normf(f,ksz)

```

c ft back to image space so lastfout will be scaled correctly
c for rmsdiff calculations ...

```

  isign=1
  iform=1
  call fourt(f,nn,ndim,isign,iform,work)
  call copyr(f,lastfout,isign,ksz)
  isign=-1
  iform=0
  call fourt(f,nn,ndim,isign,iform,work)
  call normf(f,ksz)
else
  call zero(f,ksz)
  do j=1,ks2
    lastfout(j)=0.0
  enddo
endif

```

c

```

print *, ' generate masks'
if (ispp.eq.1.and.suppo.ne.0.)then

```

```

        call maskg(mask,suppo,ksz)
elseif(ispp.eq.2)then
    do j=1,ks2
        if(cobj(j).gt.thresh)then
            mask(j) = 1.0
        else
            mask(j)=0.0
        endif
    enddo
else
    do j=1,ks2
        mask(j) = 1.0
    enddo
endif

c setting psf mask to radius of "supp"
if(suppr.ne.0.)then
    call maskg(maskr,suppr,ksz)
else
    do j=1,ks2
        maskr(j) = 1.0
    enddo
endif

c now count number of 1's in masks
nzero = 0
nzeror= 0
do j=1,ks2
    if(mask(j).ne.0.)nzero=nzero+1
    if(maskr(j).ne.0.)nzeror=nzeror+1
enddo

print *, 'nzero,nzeror',nzero,nzeror

c
c ft and normalize image for first deconvolution pass
c
    iform=0
    isign=-1
    call copyr(c,cobj,isign,ksz)
    call fourt(c,nn,ndim,isign,iform,work)
    call normf(c,ksz)

c
c perform deconvolution in loop
c
    print *, ' .....deconvolving'
    do 1000 iz=1,maxc
c ft, shift and normalize psf ...
        iform=0
        isign=-1
        call copyr(g,gref,isign,ksz)
        call fourt(g,nn,ndim,isign,iform,work)
        call shift(g,ksz)
        call normf(g,ksz)
c output = input deconvolved by psf :
c if first time through, deconvolve with beta=1.0
        if(iobj.ne.1.and.iz.eq.1)then
            call wienerf(c,g,f,ksz,cf,wol,1.0)
        else
            call wienerf(c,g,f,ksz,cf,wol,beta)
        endif
c ft output to image space, apply positivity, ft back, normalize
        iform=1
        isign=1
        call fourt(f,nn,ndim,isign,iform,work)

```

```

    call copyr(f,fout,isign,ksz)
    call posf(fout,mask,nzero,testo,testno,ksz)
    print *, ' '
    print *, ' Iteration #',iz
    write (1,*) ' '
    write (1,*) ' Iteration # ',iz
    print *, 'obj: summed neg/pos ',testo,' #neg/#pos ',testno
    write (1,*) 'obj: sum neg/pos ',testo,' #neg/#pos ',testno

c psf = input deconvolved by output ---
    iform=0
    isign=-1
    call copyr(f,fout,isign,ksz)
    call fourt(f,nn,ndim,isign,iform,work)
    call normf(f,ksz)
    call wienerf(c,f,g,ksz,cf,wpl,beta)
    call shift(g,ksz)
    iform=1
    isign=1
c ft psf to image space, centre, apply positivity
    call fourt(g,nn,ndim,isign,iform,work)
    call copyr(g,gref,isign,ksz)
    call centre(gref,tempb,ksz,ksz1)

    if(ipss.eq.1)then
        call posf(gref,maskr,nzeror,testr,testnr,ksz)
    else
        call support(gref,maskr,testr,testnr,ksz2)
    endif

    print *, 'psf: summed neg/pos ',testr,' #negs/#pos ',testnr
    write (1,*) 'psf: sum neg/pos ',testr,' #negs/#pos ',testnr

c
c testo is sum of negatives over sum of positives in output
c prior to positivity, testr is same for psf ...
c
    rmd = rmsdiff(lastfout,fout,ksz)
    print *, ' rmsdiff :',rmd
    write (1,*) ' rmsdiff :',rmd
    stats(iz,1)=testo
    stats(iz,2)=testr
    stats(iz,3)=rmd

1000    continue
c
c stop : scale total power of output to input power, psf to 1.0
c then save
c
2000    continue
    call scale(fout,power,ksz)
    rtot=0.0
    do j=1,ksz2
        rtot=rtot+fout(j)
    enddo
    print *, ' total power in image ',rtot
    call saveim(name2,fout,ksz,3)

    call scale(gref,1.0,ksz)
    call saveim(name3,gref,ksz,3)

    call saverect(name4,stats,ksz,3,ksz,3)

stop
end

```

```

      program dcw
c last edited: November 4, 1991
c Compile in IRAF using FC
c link with:  bidsubs, irafsubs, and fourt
c uses wiener deconvolution
c Allows application of a edge mask for images which extend
c beyond the frame boundary
c Best results usually obtained with square low-pass filter
c and cutoff of 1.0
c Smoothness of output image is adjusted by chnaging the wiener
c multiplier - greater value for smoother image.
c
c
      parameter (isz=512,isz1=isz/2,isz2=isz1+1)
      real*4 work(2*isz)
      real*4 ph(isz*isz),rwk(isz)
      complex snc(isz*isz),refc(isz*isz),sncft(isz*isz),sncdc(isz*isz)
      integer nn(2)
      integer iph(isz*isz)
      character name1*80,name2*80,name3*80

      print *, ''
      print *, ' ---- deconvolution using wiener filter ----'
      print *, ' ---- wiener parameter w1 : 0 => straight deconvolution ----'
      print *, ' ---- w1 >> 0 gives noise reduction ----'
      print *, ' ---- can truncate negatives at end or apply the ----'
      print *, ' ---- fienup algorithm to the output ----'
      print *, ''

      print *, ' enter input object file name '
      read (*,'(a)') name1
      print *, ' enter image dimension '
      read (*,*) ksz
      ksz2=ksz*ksz

      call loadim(name1,ph,iph,rwk,ksz,3)
      print *, ' 1 for border square mask, 2 for circular, 0 for none'
      read (*,*) isqm
      if (isqm.eq.1)then
        print *,'Enter the sqmask border width, 0 for none'
        read (*,*) iradm
      elseif(isqm.eq.2)then
        print *, ' Enter circular mask radius '
        read (*,*) radm
      endif

c apply square gaussian border
      if (isqm.eq.1)call sqmask(ph,iradm,ksz)

c apply circular gaussian border
      if (isqm.eq.2)call circmask(ph,radm,ksz)

      rintot=0.0
      do j=1,ksz2
        snc(j)=ph(j)
        rintot=rintot+ph(j)
      enddo
      print *, ' total power in image ',rintot
      print *, ' enter input reference file name '
      read (*,'(a)') name2
      call loadim(name2,ph,iph,rwk,ksz,3)
      do j=1,ksz2

```

```

        refc(j)=ph(j)
    enddo

    print *, ' enter wiener filter multiplier, 1 is default'
    read (*,*) w1
    print *, ' enter radius for wiener noise estimate (0 to 1.0) '
    read (*,*) wr
    wr=wr*ksz/2.0
    print *, ' enter low frequency cutoff, (0 to 1.0) '
    read (*,*) cf
    cf=cf*ksz/2.0
    print *, ' 1 for circular low pass filter, 2 for square filter, or 0'
    read (*,*) iflt

c set up parameters for ft
    ndim=2
    iform=0
    nn(1)=ksz
    nn(2)=ksz
    isign=-1

c ft image
    print *, ' transforming image ...'
    call fourt(snc,nn,ndim,isign,iform,work)
c ft psf
    print *, ' transforming reference ...'
    call fourt(refc,nn,ndim,isign,iform,work)

    do j=1,ks2
        sncft(j)=snc(j)
    enddo

c perform wiener deconvolution
600    print *, ' doing wiener deconvolution ...'
    call wienerd(snc,refc,ksz,wr,w1)
    do j=1,ks2
        sncdc(j)=snc(j)
    enddo

c low pass filter
650    if(cf.ne.0.) call filt(snc,ksz,cf,iflt)

c shift image to center of field
    call shift(snc,ksz)

    iform=1
    isign=1
c ft back to image space
    print *, ' transforming back to image space ...'
    call fourt(snc,nn,ndim,isign,iform,work)

    do j=1,ks2
        if(real(snc(j)).lt.0.0) snc(j)=0.0
    enddo

    do j=1,ks2
        ph(j)=real(snc(j))
    enddo

    routtot=0.0
    do j=1,ks2
        routtot=routtot+ph(j)
    enddo
    print *, 'output power before renorm ',routtot

```

```

rsfact=rintot/routtot
do j=1,ks2
    ph(j)=ph(j)*rsfact
enddo
routtot=0.0
do j=1,ks2
    routtot=routtot+ph(j)
enddo
print *, ' total output power ', routout
print *, ' enter output file name '
read (*,'(a)') name3
call saveim(name3,ph,ks2,3)

```

c again?

```

print *, ' 0 to quit, 1 to redo with new w1, 2 to redo with new cf'
read (*,*) ilp
if (ilp .eq. 0) goto 99999
if (ilp .eq. 1) then
    print *, ' enter wiener filter multiplier, 1 is default'
    read (*,*) w1
    print *, ' enter radius for wiener noise estimate (0 to 1.0) '
    read (*,*) wr
    wr = wr*ks2/2.0
    print *, ' enter low frequency cutoff, (0 to 1.0)'
    read (*,*) cf
    cf = cf*ks2/2.0
    print *, ' 1 for circular low pass filter, 2 for square filter '
    read (*,*) iflt
    do j=1,ks2
        snc(j)=sncft(j)
    enddo
    goto 600
endif
if (ilp .eq. 2) then
    print *, ' enter low frequency cutoff (0 to 1.0)'
    read (*,*) cf
    cf = cf*ks2/2.0
    print *, ' 1 for circular low pass filter, 2 for square filter '
    read (*,*) iflt
    do j=1,ks2
        snc(j)=sncdc(j)
    enddo
    goto 650
endif
99999 stop
end

```



```

c  Irafsubs.f
c      loadim : load an image (iraf, real or integer)
c      saveim : save an image (iraf or real)
c      saverect : save a rectangle chunked from corner of larger
c                  rectangle to iraf file (for saving convergence statistics)

```

```

      subroutine loadim(name,a,itmp,rwk,isz,ftyp)

```

```

c last edited july30,1990
c loads iraf files into fortran program
c itmp is an integer array, iszxisz, for loading integer
c images, rwk is a one-row working real array,
c ftyp is file-type : 1 means integer, 2 means real, 3 means iraf.
c

```

```

      character name*80
      real a(isz,isz)
      integer itmp(isz,isz)
      real rwk(isz)
      integer ftyp
      integer im
      integer axl(7)
      integer naxis
      integer dtype
      integer ier
      integer xcentr, ycentr, i1, i2, j1, j2
      integer ist,iend,jst,jend,idim,jdim
      real bsum
      isz4=isz*isz*2
      isz6=isz4*2

```

```

c
c

```

```

      if (ftyp .eq. 1) then
        open (unit=1,file=name,access='direct',status='old',
+          form='unformatted', recl=isz6)
        read (unit=1,rec=1) itmp

        open(unit=1, file=name, status='old', form='unformatted',
+          access='direct',recl=isz6)
        read(unit=1) itmp
        do j=1,isz
          do i=1,isz
            a(i,j) = itmp(i,j)
          end do
        end do
        close(unit=1)
        return
      else if (ftyp .eq. 2) then
        open (unit=1,file=name,access='direct',status='old',
+          form='unformatted', recl=isz6)
        read (unit=1,rec=1) a
        close(unit=1)
        return
      else if (ftyp .eq. 3) then
        call imopen (name, 1, im, ier)
        if (ier .ne. 0) goto 99999
        call imgsiz (im, axl, naxis, dtype, ier)
        if (ier .ne. 0) goto 99999
        if ((axl(1) .gt. isz) .or. (axl(2) .gt. isz)) then
          print *, ' image bigger than array size : '
          print *, ' axl(1): ', axl(1), ' ... axl(2): ', axl(2)
          write (*,*) 'input centre of extraction box'
          read (*,*) xcentr, ycentr
          xcentr = min ((axl(1) - isz/2), max (isz/2, xcentr))

```

```

ycentr = min ((axl(2) - isz/2), max (isz/2, ycentr))
i1 = xcentr - isz / 2 + 1
i2 = i1 + isz - 1
j1 = ycentr - isz / 2 + 1
j2 = j1 + isz - 1
call imgs2r (im, a, i1, i2, j1, j2, ier)
if (ier .ne. 0) goto 99999
else if ((axl(1) .lt. isz) .or. (axl(2) .lt.isz)) then
    idim = axl(1)
    jdim = axl(2)
    ist = (isz-idim)/2 + 1
    iend = ist+axl(1)-1
    jst = (isz-jdim)/2 + 1
    jend = jst+axl(2)-1
    do j=jst,jend
        call imgs2r(im,rwk,1,axl(1),1+j-jst,1+j-jst,ier)
        if (ier .ne. 0) goto 99999
        do i=ist,iend
            a(i,j)=rwk(i-ist+1)
        end do
    end do
    bsum=0.0
    print *, ' image smaller than array size :'
    print *,
& ' 1 to calculate average background, 0 to set to zero'
    read (*,*) iback
    if (iback .eq. 0) goto 500
    do i=ist,iend
        bsum = bsum + a(i,jst)+a(i,jend)
    end do
    do j=jst,jend
        bsum = bsum + a(ist,j)+a(iend,j)
    end do
    bsum = bsum/(2.*jdim + 2.*idim)

    write (*,*) ' average background : ',bsum
    if (jst .gt. 1) then
        do j=1,jst-1
            do i=1,isz
                a(i,j)=bsum
            end do
        end do
    end if
    if (ist .gt. 1) then
        do i=1,ist-1
            do j=jst,jend
                a(i,j)=bsum
            end do
        end do
    end if
    if (iend .lt. isz) then
        do i=iend+1,isz
            do j=jst,jend
                a(i,j)=bsum
            end do
        end do
    end if
    if (jend .lt. isz) then
        do j=jend+1,isz
            do i=1,isz
                a(i,j)=bsum
            end do
        end do
    end if
end if

```

```

        else
            i1 = 1
            i2 = axl(1)
            j1 = 1
            j2 = axl(2)
            call imgs2r (im, a, i1, i2, j1, j2, ier)
            if (ier .ne. 0) go
to 99999
        end if
        call imclos (im, ier)
        if (ier .ne. 0) goto 99999
        return
    end if
c
99999  call imemsg (ier,name)
        write (*, 2222) name
2222   format('error: ',a80)
        stop
        end
c
c-----
c
        subroutine saveim(name,a,isz,ftyp)

c last edited: July 30, 1991
c saves images as iraf files

        character name*80
        real a(isz,isz)
        integer isz
        integer ftyp
        integer axl(7),naxis,im,ier
        if (ftyp .eq. 3) then
            axl(1)=isz
            axl(2)=isz
            naxis=2
            call imcrea (name,axl,naxis,6,ier)
            if (ier .ne. 0) goto 99998
            call imopen (name,3,im,ier)
            if (ier .ne. 0) goto 99998
            call imps2r (im,a,1,isz,1,isz,ier)
            if (ier .ne. 0) goto 99998
            call imclos (im,ier)
            if (ier .ne. 0) goto 99998
            return
        else
            open (unit=1,file=name,status='new',form='unformatted',
+             access='direct',recl=4*isz*isz)
            write (unit=1,rec=1) a
            close (unit=1)
            return
        end if
99998  call imemsg (ier,name)
        write (*, 2222) name
2222   format('error: ',a80)
        stop
        end
c *****
c
        subroutine saverect(name,a,d1,d2,rd1,rd2)

c save a few lines of data for convergence plots
        character name*80
        integer d1,d2,rd1,rd2

```

```

real a(rd1,rd2)
integer axl(7),naxis,im,ier
print *, 'd1:',d1,', d2:',d2,', rd1:',rd1,', rd2:',rd2
axl(1)=d1
axl(2)=d2
naxis=2
call imcrea (name,axl,naxis,6,ier)
if (ier .ne. 0) goto 99997
call imopen (name,3,im,ier)
if (ier .ne. 0) goto 99997
call imps2r (im,a,1,d1,1,d2,ier)
if (ier .ne. 0) goto 99997
call imclos (im,ier)
if (ier .ne. 0) goto 99997
return
99997 call imemsg (ier,name)
write (*,('error: ", a80)') name
stop
end

```

c

```

c
c bidsubs.f : subroutines for idconf and makemask, etc...
c
c last edited December 6, 1991
c
c *****
c
c routines are :
c   cent : Finds center of mass
c   centre : centres the object using fmax to find psf center
c   circmask: multiply image by circular rolloff mask
c   copyr : copies real array into complex array or vice versa,
c           depending on value of isign
c   cwind : a rolloff window function in f-space
c   dtr: removes trend from solar images before BID
c   fmax : finds position and values of minimum and maximum pixels
c           in image
c   filt : apply square or circular rolloff filter using cwind at
c           given radius ...
c   maskg: Generates gaussian masked image
c   normf : normalizes in fourier space so a(1,1)=1
c   pcent : print array center
c   posf : the old version (and best working, it seems) of pos,
c           iteratively truncates negatives and adds them back in ...
c   rmsdiff : rmsdiff between two images (real), then stuffs second
c           image into first ...
c   rolloff : rolls off high frequencies using cwind
c   scale : scales image to given power level
c   shift : reverses sign of every other element in ft, shifts
c           object from center to corners or vice versa ...
c   sqmask: Generate edge rolloff mask for solar images
c   subtract: Subtracts low frequencies for solar detrending
c   support: Applies image plane support constraint for BID
c   wienerd : wiener filter deconvolution, with averaging in of
c           previous f (f = (1.0-beta)*f+beta*c/g)
c   wienerf : another version of wienerd
c   zero : zeros a complex array
c
c *****
c
c   subroutine cent(ci,cj,tm,ph,isz)
c
c calculates center of mass of iszxisz image
c
c xm = x coordinate of centre of mass
c ym = y coordinate of centre of mass
c tm = running sum of values in image array
c ph() = image array
c isz = characteristic image dimension (ie. 128)
c
c   dimension ph(isz,isz)
c   real copy
c
c   call fmax(amax, amin,imax,jmax,imin,jmin, ph, isz)
c   amm=0.3*amax
c
c   z1=isz/2
c   z2=isz1+1
c   tm=0.
c   xc1=0.
c   yc1=0.
c   do j=1,isz
c     do i=1,isz
c       copy = ph(i,j)

```

```

        if (copy.ge.amm) then
            tm=tm+copy
            xc1=copy*i+xc1
            yc1=copy*j+yc1
        endif
    enddo
enddo

ci=xc1/tm
cj=yc1/tm
print *, ' center at ',ci,cj

return
end

```

```

C
C *****
C

```

```

subroutine centre(a, b, isz, isz1)
real a(isz, isz), b(isz, isz)

call cent(ci, cj, t, a, isz)

do j = 1, isz
do i = 1, isz
b(i, j) = 0.0
end do
end do
jr = (nint(cj) - isz1) - .5
ir = (nint(ci) - isz1) - .5
do j = 1, isz
do i = 1, isz
il = i + ir

```

c centre object

```

    j1 = j + jr
    if (((il .le. isz) .and. (il .ge. 1)) .and. (j1 .le. isz)) .and.
&(j1 .ge. 1)) then
b(i, j) = a(il, j1)
end if
end do
end do
do j = 1, isz
do i = 1, isz
a(i, j) = b(i, j)
end do
end do
return
end

```

```

C
C *****

```

```

subroutine circmask(obj, radm, ksz)
real obj(ksz, ksz), radm

ksz1=ksz/2
ksz2=ksz1+1
rr=ksz2-radm
if(rr.lt.1)rr=1.
do j=1, ksz
do i=1, ksz
r=sqrt(1.*(ksz2-i)**2+1.*(ksz2-j)**2)
if(r.ge.radm)then
obj(i, j)=obj(i, j)*cwind(abs(r-radm)/rr)

```

```

        endif

        enddo
    enddo

    return
end

c *****

c
    subroutine copyr(a,ar,isign,isz)
    complex a(isz,isz)
    real    ar(isz,isz)
    if(isign.eq.1)then
c copy into real array for pos
        do j=1,isz
            do i=1,isz
                ar(i,j)=real(a(i,j))
            enddo
        enddo
    else
c copy into real array for pos
        do j=1,isz
            do i=1,isz
                a(i,j)=ar(i,j)
            enddo
        enddo
    endif

    return
end

c
c *****
    function cwind(relr)
c    A window for fft's that has low sidelobes
    real c(4)
    data c / .074, .302, .233, .390 /
    if (relr .lt. 0.) stop 'cwind'
c careful ...
    if (relr .gt. 1.5) then
        cwind = 0.
    else
c (1-r**2), r=0... 1.0
        r = 1. - (relr * relr)
        r2 = r * r
        r3 = r2 * r
        cwind = ((c(1) + (r * c(2))) + (r2 * c(3))) + (r3 * c(4))
c let go all the way to zero
        if (cwind .lt. 0.) cwind = 0.
    end if
    return
end

c
c *****

    subroutine dtr(a,work,ac,acf,ksz,fc,dc)
c subtract out the low frequency trend in an image, then add dc to
c make image positive ...
    real a(ksz*ksz),work(2*ksz)
    complex ac(ksz*ksz),acf(ksz*ksz)
    integer*4 nn(2),ndim,isign,iform

```



```

power=0.0
ksz2=ksz*ksz
do j=1,ksz2
    ac(j)=(0.,0.)
    ac(j)=a(j)
enddo

```

C

```

ndim=2
nn(1)=ksz
nn(2)=ksz
iform=0
isign=-1
call fourt(ac,nn,ndim,isign,iform,work)
do j=1,ksz2
    acf(j)=ac(j)
enddo
call filt(acf,ksz,fc,2)
call subtract(ac,acf,ksz)
iform=1
isign=1
call fourt(ac,nn,ndim,isign,iform,work)
do j=1,ksz2
    a(j)=real(ac(j)/ksz2)
enddo
call fmax(amax,amin,imax,jmax,imin,jmin,a,ksz)
do j=1,ksz2
    a(j)=a(j)-amin
enddo
dc=-amin
return
end

```

C

C *****

C

```

subroutine fmax(amax, amin, imax, jmax, imin, jmin, ph, isz)
dimension ph(isz, isz)
amax = ph(1,1)
amin = ph(1,1)
do j = 1, isz
do i = 1, isz
if (ph(i,j) .gt. amax) then
amax = ph(i,j)
imax = i
jmax = j
end if
if (ph(i,j) .lt. amin) then
amin = ph(i,j)
imin = i
jmin = j
end if
end do
end do
return
end

```

C

C *****

C

```

subroutine filt(cobj,isz,cf,isq)
complex cobj(isz,isz)
isz1=isz/2

```

C low pass filter

C

```

650     if(cf.ne.0.0.and.isq.eq.1)then
c circular filter
      print *, 'circular low pass filter ...'
      do 100 j=1,isz1
        do 100 i=1,isz1
          d1=sqrt((i-1.)**2+(j-1.)**2)/cf
          d2=sqrt((i-1.)**2+j**2)/cf
          d3=sqrt(i**2+(j-1.)**2)/cf
          d4=sqrt(1.*i**2+j**2)/cf
          cobj(i,j)=cwind(d1)*cobj(i,j)
          cobj(i,isz+1-j)=cwind(d2)*cobj(i,isz+1-j)
          cobj(isz+1-i,j)=cwind(d3)*cobj(isz+1-i,j)
          cobj(isz+1-i,isz+1-j)=cwind(d4)*cobj(isz+1-i,isz+1-j)
100      continue
      endif
c
      if(cf.ne.0.0.and.isq.eq.2)then
c square filter
      print *, 'square low pass filter'
      do 200 j=1,isz1
        do 200 i=1,isz1
          d1x=(i-1.)/cf
          d1y=(j-1.)/cf
          d2x=(i-1.)/cf
          d2y=j/cf
          d3x=i/cf
          d3y=(j-1.)/cf
          d4x=i/cf
          d4y=j/cf
          cobj(i,j)=cwind(d1x)*cwind(d1y)*cobj(i,j)
          cobj(i,isz+1-j)=cwind(d2x)*cwind(d2y)*cobj(i,isz+1-j)
          cobj(isz+1-i,j)=cwind(d3x)*cwind(d3y)*cobj(isz+1-i,j)
          cobj(isz+1-i,isz+1-j)=cwind(d4x)*cwind(d4y)
+          *cobj(isz+1-i,isz+1-j)
200      continue
      endif
c
c
      return
      end

```

```

c *****
subroutine gauss(a,wid,krn,isz)
real a(isz,isz)
real wid
integer seed
      seed=13972
      isz1=isz/2
      isz2=isz1+1

      if (krn .eq. 1) then
        x=rand(seed)
        do j=1,97
          x=rand(0)
        enddo
      endif

      wid2=wid*wid

      do j=1,isz
        do i=1,isz

```

```

        r2=((isz2-i)**2+(isz2-j)**2)
        r3=r2/wid2
        if (r3 .le. 50) then
            if(krn.eq.1) then
                rr=rand(0)
            else
                rr=1.
            endif
            a(i,j)=exp(-r2/wid)*rr
        endif
    enddo
enddo
return
end

```

C *****

```

subroutine maskg(m,rd,ksz)
real    m(ksz,ksz)

ksz1=ksz/2
do j=1,ksz
    do i=1,ksz
        r=sqrt(float(ksz1-i)**2+float(ksz1-j)**2)
        if(r.le.rd)then
            m(i,j)=1.0
        else
            m(i,j)=0.0
        endif
    enddo
enddo
return
end

```

C *****

C

```

subroutine normf(a, isz)
complex a(isz, isz)
a1 = cabs(a(1,1))
if (a1 .eq. 0.0) then
    print *, ' error in normf: a(1,1)=0.0'
    return
endif
do j = 1, isz
    do i = 1, isz
        a(i,j) = a(i,j) / a1
    end do
end do
return
end

```

C

C *****

```

subroutine pcent(a,ksz)
real a(ksz,ksz)
do j=ksz/2-3,ksz/2+4
    print 111, (a(i,j),i=ksz/2-3,ksz/2+4)
enddo
111 format(8e10.2)
return
end

```

C *****

C

```

subroutine posf(a, b, nzero, test, testn, isz)

```

c modify 12/23/1991

```
real a(isz, isz), b(isz, isz)
integer nzero
```

c 1st apply support constraint

```
if(nzero.ne.0)then
  do j = 1, isz
    do i = 1, isz
      a(i,j) = (a(i,j) * b(i,j)) / nzero
    end do
  end do
else
  print *, ' mask is all zeros'
  return
endif
```

c then truncate negatives

```
do jz=1,3

  sump = 0.0
  sumn = 0.0
  npos = 0
  nneg = 0
  do j = 1, isz
    do i = 1, isz
      if (a(i,j) .lt. 0.0) then
        sumn = sumn + a(i,j)
        a(i,j) = 0.0
        nneg=nneg+1
      elseif (a(i,j) .gt. 0.0)then
        sump = sump + a(i,j)
        npos = npos + 1
      end if
    end do
  end do
  if (jz .eq. 1)then
    if(sump.ne.0)then
      test = abs(sumn / sump)
    else
      print *, ' Image all negs'
      return
    endif
    if(npos.ne.0)then
      testn=float(nneg)/npos
    else
      print *, ' No positives in image'
    endif
  endif
endif
```

c now add in negatives to keep energy constant

```
ss = sumn /nzero
do j = 1, isz
  do i = 1, isz
    if (b(i,j) .eq. 1.0) then
      a(i,j) = a(i,j) + ss
    end if
  end do
end do
```

enddo

c now find min and max and rescale

```

c      call fffmax(amax,amin,imax,jmax,imin,jmin,a,isz)
c      amm=amax-amin
c      do j=1,isz
c          do i=1,isz
c              a(i,j)=(a(i,j)-amin)/amm
c              if(a(i,j).lt.0.)a(i,j)=0.0
c          enddo
c      enddo

c      return
c      end

c
c      *****
c
c      function rmsdiff(a1,a2,isz)
c      real a1(isz,isz), a2(isz,isz)
c      fsum = 0.0
c      do j = 1, isz
c          do i = 1, isz
c              fsum = fsum + (a1(i,j) - a2(i,j))**2
c              a1(i,j) = a2(i,j)
c          end do
c      end do
c      rmsdiff = sqrt (fsum)
c      return
c      end

c
c      *****
c
c      subroutine rolloff(a,cf,isz)
c      complex a(isz,isz)
c      real cf
c      isz1=isz/2
c      do j=1,isz1
c          do i=1,isz1
c              d1=sqrt((i-1.)**2+(j-1.)**2)/cf
c              d2=sqrt((i-1.)**2+(j)**2)/cf
c              d3=sqrt((i)**2+(j-1.)**2)/cf
c              d4=sqrt((1.*i)**2+(1.*j)**2)/cf
c              a(i,j)=a(i,j)*cwind(d1)
c              a(i,isz+1-j)=a(i,isz+1-j)*cwind(d2)
c              a(isz+1-i,j)=a(isz+1-i,j)*cwind(d3)
c              a(isz+1-i,isz+1-j)=a(isz+1-i,isz+1-j)*cwind(d4)
c          enddo
c      enddo
c      return
c      end

c
c      *****
c
c
c
c
c      subroutine scale(a,power,isz)
c      real a(isz,isz), power
c      real sum
c      sum=0.0
c      do j=1,isz
c          do i=1,isz
c              sum = sum + abs(a(i,j))
c          enddo
c      enddo
c      rsc = power/sum
c      do j=1,isz
c          do i=1,isz

```

```

        a(i,j) = a(i,j)*rsc
    enddo
enddo
return
end

```

```

C
C *****
C
    subroutine shift(ph,nar)
C
C     shifts an image from origin to center by negating every other
C     frequency
    complex ph(nar,nar)
C
    if(mod(nar,2).eq.0)then
        n1=nar-1
        n2=nar
    else
        n1=nar
        n2=nar-1
    endif

    do j=2,n2,2
        do i=1,n1,2
            ph(i,j)=-ph(i,j)
            ph(j,i)=-ph(j,i)
        enddo
    enddo
C
    return
end

```

```

C *****
C
    subroutine sqmask(obj,iradm,isz)
    real obj(isz,isz)
    integer iradm

    do j=1,isz
        do i=1,iradm
            clc=(1.*iradm-i)/(1.*iradm)
            obj(i,j)=obj(i,j)*cwind(clc)
            obj(j,i)=obj(j,i)*cwind(clc)
            obj(isz-i+1,j)=obj(isz-i+1,j)*cwind(clc)
            obj(j,isz-i+1)=obj(j,isz-i+1)*cwind(clc)
        enddo
    enddo
    return
end

```

```

C *****
C
    subroutine subtract(ac,acf,ksz)
    complex ac(ksz,ksz),acf(ksz,ksz)
    do j=1,ksz
        do i=1,ksz
            ac(i,j)=ac(i,j)-acf(i,j)
        enddo
    enddo
C
    ac(1,1)=cabs(acf(1,1))
    return

```

```

end
c
c*****

      subroutine support(a,mask,test,testn,ksz2)
c Apply support only to psf
      real a(ksz2), mask(ksz2)
      sump=0.
      sumn=0.
      npos=0
      nneg=0
      do j=1,ksz2
        a(j)=a(j)*mask(j)
        if(a(j).gt.0.)then
          sump=sump+a(j)
          npos=npos+1
        endif
        if(a(j).lt.0.)then
          sumn=sumn+a(j)
          nneg=nneg+1
        endif
      enddo
      test=abs(sumn/sump)
      testn=float(nneg)/npos

      return
      end

c *****
      subroutine wienerd(sig,ref,isz,cf,w1)
      complex sig(isz,isz)
      complex ref(isz,isz)
c
      isz1=isz/2
c 1st calc const level for wiener minimum
      icf=cf
      if(icf.gt.isz1)icf=isz1
      at=0.0
      nn=0
      do 100 j=1,isz1
        do 100 i=1,isz1
          id1=sqrt((i-1.)**2+(j-1.)**2)+0.5
          id2=sqrt((i-1.)**2+(j)**2)+0.5
          id3=sqrt((i)**2+(j-1.)**2)+0.5
          id4=sqrt((1.*i)**2+(1.*j)**2)+0.5
          if(id1.eq.icf)then
            at = at+cabs(ref(i,j))
            nn=nn+1
          endif
          if(id2.eq.icf)then
            at = at+cabs(ref(i,isz+1-j))
            nn=nn+1
          endif
          if(id3.eq.icf)then
            at = at+cabs(ref(isz+1-i,j))
            nn=nn+1
          endif
          if(id4.eq.icf)then
            at = at+cabs(ref(isz+1-i,isz+1-j))
            nn=nn+1
          endif
        enddo
      enddo
100 continue

```



```

c
    at=w1*at/nn
    print *, ' Wiener filter constant ',at
    at2=at*at
c
c perform wiener division
    do 200 j=1,isz
        do 200 i=1,isz
            bbl=cabs(ref(i,j))**2+at2
            if(bbl.ne.0.0)then
                sig(i,j)=sig(i,j)*conjg(ref(i,j))/(bbl)
            else
                sig(i,j) =0.0
            end if
200    continue
c
    return
end

c
c *****

    subroutine wienerf(c,g,f,isz,cf,w1,beta)
c wiener filter for BID.  Adds fraction of previous iteration to
c wiener filtered result

    complex c(isz,isz)
    complex g(isz,isz),f(isz,isz)
    real beta,w1,cf

    isz1=isz/2
c 1st calc const level for wiener minimum
    icf=cf
    if(icf.gt.isz1)icf=isz1
    at=0.0
    nn=0
    do j=1,isz1
        do i=1,isz1
            id1=sqrt((i-1.)**2+(j-1.)**2)+0.5
            id2=sqrt((i-1.)**2+(j)**2)+0.5
            id3=sqrt((i)**2+(j-1.)**2)+0.5
            id4=sqrt((1.*i)**2+(1.*j)**2)+0.5
            if(id1.eq.icf)then
                at = at+cabs(g(i,j))
                nn=nn+1
            endif
            if(id2.eq.icf)then
                at = at+cabs(g(i,isz+1-j))
                nn=nn+1
            endif
            if(id3.eq.icf)then
                at = at+cabs(g(isz+1-i,j))
                nn=nn+1
            endif
            if(id4.eq.icf)then
                at = at+cabs(g(isz+1-i,isz+1-j))
                nn=nn+1
            endif
        enddo
    enddo

    at=w1*at/nn
    at2=at*at

```

```

c perform wiener division
  do j=1,isz
    do i=1,isz
      bbl=cabs(g(i,j))**2+at2
      if(bbl.ne.0.0)then
        f(i,j)=(1.0-beta)*f(i,j)+beta*c(i,j)*conjg(g(i,j))/(bbl)
      end if
    enddo
  enddo

  return
end

```

```

c
c*****
c
c

```

```

  subroutine zero(a,isz)
    complex a(isz,isz)
    do j=1,isz
      do i=1,isz
        a(i,j)=0.0
      enddo
    enddo
    return
  end

```

```

C  Fourt.f
C  NN, ISIGN AND IFORM MUST ALL
C  BE DIMENSIONED INTEGER*4 !!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
C  THE FAST FOURIER TRANSFORM IN USASI BASIC FORTRAN
C
C
C
C  TRANSFORM(J1,J2,...) = SUM(DATA(I1,I2,...)*W1**((I1-1)*(J1-1))
C
C                        *W2**((I2-1)*(J2-1))*...),
C
C  WHERE I1 AND J1 RUN FROM 1 TO NN(1) AND W1=EXP(ISIGN*2*PI*
C  SQRT(-1)/NN(1)), ETC.  THERE IS NO LIMIT ON THE DIMENSIONALITY
C  (NUMBER OF SUBSCRIPTS) OF THE DATA ARRAY.  IF AN INVERSE
C  TRANSFORM (ISIGN=+1) IS PERFORMED UPON AN ARRAY OF TRANSFORMED
C  (ISIGN=-1) DATA, THE ORIGINAL DATA WILL REAPPEAR,
C  MULTIPLIED BY NN(1)*NN(2)*...  THE ARRAY OF INPUT DATA MAY BE
C  REAL OR COMPLEX, AT THE PROGRAMMERS OPTION, WITH A SAVING OF
C  UP TO FORTY PER CENT IN RUNNING TIME FOR REAL OVER COMPLEX.
C  (FOR FASTEST TRANSFORM OF REAL DATA, NN(1) SHOULD BE EVEN.)
C
C  THE TRANSFORM VALUES ARE ALWAYS COMPLEX, AND ARE RETURNED IN THE
C  ORIGINAL ARRAY OF DATA, REPLACING THE INPUT DATA.  THE LENGTH
C  OF EACH DIMENSION OF THE DATA ARRAY MAY BE ANY INTEGER.  THE
C  PROGRAM RUNS FASTER ON COMPOSITE INTEGERS THAN ON PRIMES, AND IS
C  PARTICULARLY FAST ON NUMBERS RICH IN FACTORS OF TWO.
C
C
C  TIMING IS IN FACT GIVEN BY THE FOLLOWING FORMULA.  LET NTOT BE THE
C  TOTAL NUMBER OF POINTS (REAL OR COMPLEX) IN THE DATA ARRAY, THAT
C  IS, NTOT=NN(1)*NN(2)*...  DECOMPOSE NTOT INTO ITS PRIME FACTORS,
C  SUCH AS 2**K2 * 3**K3 * 5**K5 * ...  LET SUM2 BE THE SUM OF ALL
C  THE FACTORS OF TWO IN NTOT, THAT IS, SUM2 = 2*K2.  LET SUMF BE
C  THE SUM OF ALL OTHER FACTORS OF NTOT, THAT IS, SUMF = 3*K3+5*K5+..
C  THE TIME TAKEN BY A MULTIDIMENSIONAL TRANSFORM ON THESE NTOT DATA
C  POINT ADD TIME = SIX MICROSECONDS), T = 3000 + NTOT*(600+40*SUM2+
C  IS T = T0 + NTOT*(T1+T2*SUM2+T3*SUMF).  ON THE CDC 3300 (FLOATING
C  175*SUMF) MICROSECONDS ON COMPLEX DATA.
C
C  IMPLEMENTATION OF THE DEFINITION BY SUMMATION WILL RUN IN A TIME
C
C

```

PROPORTIONAL TO $NTOT * (NN(1) + NN(2) + \dots)$. FOR HIGHLY COMPOSITE $NTOT$ THE SAVINGS OFFERED BY THIS PROGRAM CAN BE DRAMATIC. A ONE-DIMENSIONAL ARRAY 4000 IN LENGTH WILL BE TRANSFORMED IN $4000 * (600 + 40 * (2+2+2+2+2) + 175 * (5+5+5)) = 14.5$ SECONDS VERSUS ABOUT $4000 * 4000 * 175 = 2800$ SECONDS FOR THE STRAIGHTFORWARD TECHNIQUE.

THE FAST FOURIER ALGORITHM PLACES TWO RESTRICTIONS UPON THE NATURE OF THE DATA BEYOND THE USUAL RESTRICTION THAT THE DATA FORM ONE CYCLE OF A PERIODIC FUNCTION. THEY ARE--

1. THE NUMBER OF INPUT DATA AND THE NUMBER OF TRANSFORM VALUES MUST BE THE SAME.
2. CONSIDERING THE DATA TO BE IN THE TIME DOMAIN, THEY MUST BE EQUI-SPACED AT INTERVALS OF DT . FURTHER, THE TRANSFORM VALUES, CONSIDERED TO BE IN FREQUENCY SPACE, WILL BE EQUI-SPACED FROM 0 TO $2 * \pi * (NN(I) - 1) / (NN(I) * DT)$ AT INTERVALS OF $2 * \pi / (NN(I) * DT)$ FOR EACH DIMENSION OF LENGTH $NN(I)$. OF COURSE, DT NEED NOT BE THE SAME FOR EVERY DIMENSION.

THE CALLING SEQUENCE IS--

CALL FOURT(DATA, NN, NDIM, ISIGN, IFORM, WORK)

DATA IS THE ARRAY USED TO HOLD THE REAL AND IMAGINARY PARTS OF THE DATA ON INPUT AND THE TRANSFORM VALUES ON OUTPUT. IT IS A MULTIDIMENSIONAL FLOATING POINT ARRAY, WITH THE REAL AND IMAGINARY PARTS OF A DATUM STORED IMMEDIATELY ADJACENT IN STORAGE (SUCH AS FORTRAN IV PLACES THEM). THE EXTENT OF EACH DIMENSION IS GIVEN IN THE INTEGER ARRAY NN, OF LENGTH NDIM. ISIGN IS -1 TO INDICATE A FORWARD TRANSFORM (EXPONENTIAL SIGN IS -) AND +1 FOR AN INVERSE TRANSFORM (SIGN IS +). IFORM IS +1 IF THE DATA AND THE TRANSFORM VALUES ARE COMPLEX. IT IS 0 IF THE DATA ARE REAL BUT THE TRANSFORM VALUES ARE COMPLEX. IF IT IS 0, THE IMAGINARY PARTS OF THE DATA SHOULD BE SET TO ZERO. AS EXPLAINED ABOVE, THE

TRANSFORM VALUES ARE ALWAYS COMPLEX AND ARE STORED IN ARRAY DATA.
WORK IS AN ARRAY USED FOR WORKING STORAGE. IT IS NOT NECESSARY
IF ALL THE DIMENSIONS OF THE DATA ARE POWERS OF TWO. IN THIS CASE
IT MAY BE REPLACED BY 0 IN THE CALLING SEQUENCE. THUS, USE OF
POWERS OF TWO CAN FREE A GOOD DEAL OF STORAGE. IF ANY DIMENSION
IS NOT A POWER OF TWO, THIS ARRAY MUST BE SUPPLIED. IT IS
FLOATING POINT, ONE DIMENSIONAL OF LENGTH EQUAL TO TWICE THE
LARGEST ARRAY DIMENSION (I.E., NN(I)) THAT IS NOT A POWER OF
TWO. THEREFORE, IN ONE DIMENSION FOR A NON POWER OF TWO,
WORK OCCUPIES AS MANY STORAGE LOCATIONS AS DATA. IF SUPPLIED,
WORK MUST NOT BE THE SAME ARRAY AS DATA. ALL SUBSCRIPTS OF ALL
ARRAYS BEGIN AT ONE.

EXAMPLE 1. THREE-DIMENSIONAL FORWARD FOURIER TRANSFORM OF A
COMPLEX ARRAY DIMENSIONED 32 BY 25 BY 13 IN FORTRAN IV.
COMPLEX ARRAY DIMENSIONED 32 BY 25 BY 13 IN FORTRAN IV.

DIMENSION DATA(32,25,13),WORK(50),NN(3)

COMPLEX DATA

DATA NN/32,25,13/

DO 1 I=1,32

DO 1 J=1,25

DO 1 K=1,13

1 DATA(I,J,K)=COMPLEX VALUE

CALL FOURT(DATA,NN,3,-1,1,WORK)

EXAMPLE 2. ONE-DIMENSIONAL FORWARD TRANSFORM OF A REAL ARRAY OF
LENGTH 64 IN FORTRAN II.

DIMENSION DATA(2,64)

DO 2 I=1,64

DATA(1,I)=REAL PART

2 DATA(2,I)=0.

CALL FOURT(DATA,64,1,-1,0,0)

THERE ARE NO ERROR MESSAGES OR ERROR HALTS IN THIS PROGRAM. THE
PROGRAM RETURNS IMMEDIATELY IF NDM OR ANY NN(I) IS LESS THAN ONE.

PROGRAM BY NORMAN BRENNER FROM THE BASIC PROGRAM BY CHARLES
RADER (BOTH OF MIT LINCOLN LABORATORY). MAY 1967. THE IDEA
FOR THE DIGIT REVERSAL WAS SUGGESTED BY RALPH ALTER (ALSO MIT LL).
THIS IS THE FASTEST AND MOST VERSATILE VERSION OF THE FFT KNOWN
TO THE AUTHOR. A PROGRAM CALLED FOUR2 IS AVAILABLE THAT ALSO
PERFORMS THE FAST FOURIER TRANSFORM AND IS WRITTEN IN USASI BASIC
FORTRAN. IT IS ABOUT ONE THIRD AS LONG AND RESTRICTS THE
DIMENSIONS OF THE INPUT ARRAY (WHICH MUST BE COMPLEX) TO BE POWERS
OF TWO. ANOTHER PROGRAM, CALLED FOUR1, IS ONE TENTH AS LONG AND
RUNS TWO THIRDS AS FAST ON A ONE-DIMENSIONAL COMPLEX ARRAY WHOSE
LENGTH IS A POWER OF TWO.

REFERENCE--

FAST FOURIER TRANSFORMS FOR FUN AND PROFIT, W. GENTLEMAN AND
G. SANDE, 1966 FALL JOINT COMPUTER CONFERENCE.

THE WORK REPORTED IN THIS DOCUMENT WAS PERFORMED AT LINCOLN LAB-
ORATORY, A CENTER FOR RESEARCH OPERATED BY MASSACHUSETTS INSTITUTE
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```
subroutine fourt(data, nn, ndim, isign, iform, work)
dimension data(1), nn(1), ifact(32), work(1)
```

```
# 126 "fourf.for"
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```
twopi = 6.283185307
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```
rthlf = .7071067812
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```
if (ndim - 1) 920, 1, 1
```

```
1 ntot = 2
```

```
do 2 idim = 1, ndim
```

```
if (nn(idim)) 920, 920, 2
```

MAIN LOOP FOR EACH DIMENSION

```

# 132 "fourth.for"
      2 ntot = ntot * nn(idim)
# 136 "fourth.for"
      np1 = 2
      do 910 idim = 1, ndim
      n = nn(idim)
      np2 = np1 * n

C
C
C      IS N A POWER OF TWO AND IF NOT, WHAT ARE ITS FACTORS
C
C
C
# 140 "fourth.for"
      if (n - 1) 920, 900, 5
# 144 "fourth.for"
      5 m = n
      ntwo = np1
      if = 1
      idiv = 2
10  iquot = m / idiv
      irem = m - (idiv * iquot)
      if (iquot - idiv) 50, 11, 11
11  if (irem) 20, 12, 20
12  ntwo = ntwo + ntwo
      ifact(if) = idiv
      if = if + 1
      m = iquot
      goto 10
20  idiv = 3
      inon2 = if
30  iquot = m / idiv
      irem = m - (idiv * iquot)
      if (iquot - idiv) 60, 31, 31
31  if (irem) 40, 32, 40
32  ifact(if) = idiv
      if = if + 1
      m = iquot
      goto 30
40  idiv = idiv + 2
      goto 30
50  inon2 = if
      if (irem) 60, 51, 60
51  ntwo = ntwo + ntwo
      goto 70
60  ifact(if) = m

C
C
C      SEPARATE FOUR CASES--
C
C      1. COMPLEX TRANSFORM
C
C      2. REAL TRANSFORM FOR THE 2ND, 3RD, ETC. DIMENSION.  METHOD--
C
C      TRANSFORM HALF THE DATA, SUPPLYING THE OTHER HALF BY CON-
C
C      JUGATE SYMMETRY.
C
C      3. REAL TRANSFORM FOR THE 1ST DIMENSION, N ODD.  METHOD--
C
C      SET THE IMAGINARY PARTS TO ZERO.
C
C      4. REAL TRANSFORM FOR THE 1ST DIMENSION, N EVEN.  METHOD--
C

```



```

150 j = j + m
c
c
c      SHUFFLE DATA BY DIGIT REVERSAL FOR GENERAL N
c
c
c
# 235 "fourth.for"
      goto 300
# 239 "fourth.for"
200 nwork = 2 * n
      do 270 i1 = 1, np1, 2
        do 270 i3 = i1, ntot, np2
          j = i3
          do 260 i = 1, nwork, 2
            if (icase - 3) 210, 220, 210
210 work(i) = data(j)
            work(i + 1) = data(j + 1)
            goto 240
220 work(i) = data(j)
            work(i + 1) = 0.
240 ifp2 = np2
            if = ifmin
250 ifp1 = ifp2 / ifact(if)
            j = j + ifp1
            if ((j - i3) - ifp2) 260, 255, 255
255 j = j - ifp2
            ifp2 = ifp1
            if = if + 1
            if (ifp2 - np1) 260, 260, 250
260 continue
            i2max = (i3 + np2) - np1
            i = 1
            do 270 i2 = i3, i2max, np1
              data(i2) = work(i)
              data(i2 + 1) = work(i + 1)
c      MAIN LOOP FOR FACTORS OF TWO.
c
c      W=EXP(ISIGN*2*PI*SQRT(-1)*M/(4*MMAx)).  CHECK FOR W=ISIGN*SQRT(-1)
c
c      AND REPEAT FOR W=W*(1+ISIGN*SQRT(-1))/SQRT(2).
c
c
c
# 265 "fourth.for"
270 i = i + 2
# 270 "fourth.for"
300 if (ntwo - np1) 600, 600, 305
305 npltw = np1 + np1
      ipar = ntwo / np1
310 if (ipar - 2) 350, 330, 320
320 ipar = ipar / 4
      goto 310
330 do 340 i1 = 1, ilrng, 2
      do 340 k1 = i1, ntot, npltw
        k2 = k1 + np1
        tempr = data(k2)
        tempi = data(k2 + 1)
        data(k2) = data(k1) - tempr
        data(k2 + 1) = data(k1 + 1) - tempi
        data(k1) = data(k1) + tempr
340 data(k1 + 1) = data(k1 + 1) + tempi
350 mmax = np1
360 if (mmax - (ntwo / 2)) 370, 600, 600

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```

370 lmax = max0(npltw,mmax / 2)
do 570 l = npl, lmax, npltw
  m = 1
  if (mmax - npl) 420, 420, 380
380 theta = - ((twopi * float(l)) / float(4 * mmax))
  if (isign) 400, 390, 390
390 theta = - theta
400 wr = cos(theta)
  wi = sin(theta)
410 w2r = (wr * wr) - (wi * wi)
  w2i = (2. * wr) * wi
  w3r = (w2r * wr) - (w2i * wi)
  w3i = (w2r * wi) + (w2i * wr)
420 do 530 il = 1, ilrng, 2
  kmin = il + (ipar * m)
  if (mmax - npl) 430, 430, 440
430 kmin = il
440 kdif = ipar * mmax
450 kstep = 4 * kdif
  if (kstep - ntwo) 460, 460, 530
460 do 520 k1 = kmin, ntot, kstep
  k2 = k1 + kdif
  k3 = k2 + kdif
  k4 = k3 + kdif
  if (mmax - npl) 470, 470, 480
470 u1r = data(k1) + data(k2)
  u1i = data(k1 + 1) + data(k2 + 1)
  u2r = data(k3) + data(k4)
  u2i = data(k3 + 1) + data(k4 + 1)
  u3r = data(k1) - data(k2)
  u3i = data(k1 + 1) - data(k2 + 1)
  if (isign) 471, 472, 472
471 u4r = data(k3 + 1) - data(k4 + 1)
  u4i = data(k4) - data(k3)
  goto 510
472 u4r = data(k4 + 1) - data(k3 + 1)
  u4i = data(k3) - data(k4)
  goto 510
480 t2r = (w2r * data(k2)) - (w2i * data(k2 + 1))
  t2i = (w2r * data(k2 + 1)) + (w2i * data(k2))
  t3r = (wr * data(k3)) - (wi * data(k3 + 1))
  t3i = (wr * data(k3 + 1)) + (wi * data(k3))
  t4r = (w3r * data(k4)) - (w3i * data(k4 + 1))
  t4i = (w3r * data(k4 + 1)) + (w3i * data(k4))
  u1r = data(k1) + t2r
  u1i = data(k1 + 1) + t2i
  u2r = t3r + t4r
  u2i = t3i + t4i
  u3r = data(k1) - t2r
  u3i = data(k1 + 1) - t2i
  if (isign) 490, 500, 500
490 u4r = t3i - t4i
  u4i = t4r - t3r
  goto 510
500 u4r = t4i - t3i
  u4i = t3r - t4r
510 data(k1) = u1r + u2r
  data(k1 + 1) = u1i + u2i
  data(k2) = u3r + u4r
  data(k2 + 1) = u3i + u4i
  data(k3) = u1r - u2r
  data(k3 + 1) = u1i - u2i
  data(k4) = u3r - u4r
520 data(k4 + 1) = u3i - u4i

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        kdif = kstep
        kmin = (4 * (kmin - il)) + il
        goto 450
530 continue
        m = m + lmax
        if (m - mmax) 540, 540, 570
540 if (isign) 550, 560, 560
550 tempr = wr
        wr = (wr + wi) * rthlf
        wi = (wi - tempr) * rthlf
        goto 410
560 tempr = wr
        wr = (wr - wi) * rthlf
        wi = (tempr + wi) * rthlf
        goto 410
570 continue
        ipar = 3 - ipar
        mmax = mmax + mmax
C
C
C     MAIN LOOP FOR FACTORS NOT EQUAL TO TWO.
C
C     W=EXP(ISIGN*2*PI*SQRT(-1)*(J1+J2-I3-1)/IFP2)
C
C
C
# 369 "fourth.for"
        goto 360
# 374 "fourth.for"
        600 if (non2p - 1) 700, 700, 601
        601 ifp1 = ntwo
            if = inon2
        610 ifp2 = ifact(if) * ifp1
            theta = - (twopi / float(ifact(if)))
            if (isign) 612, 611, 611
        611 theta = - theta
        612 wstpr = cos(theta)
            wstpi = sin(theta)
            do 650 j1 = 1, ifp1, np1
                thetm = - ((twopi * float(j1 - 1)) / float(ifp2))
                if (isign) 614, 613, 613
        613 thetm = - thetm
        614 wminr = cos(thetm)
            wmini = sin(thetm)
            ilmax = (j1 + ilrng) - 2
            do 650 il = j1, ilmax, 2
                do 650 i3 = il, ntot, np2
                    i = 1
                    wr = wminr
                    wi = wmini
                    j2max = (i3 + ifp2) - ifp1
                    do 640 j2 = i3, j2max, ifp1
                        twowr = wr + wr
                        j3max = (j2 + np2) - ifp2
                        do 630 j3 = j2, j3max, ifp2
                            jmin = (j3 - j2) + i3
                            j = (jmin + ifp2) - ifp1
                            sr = data(j)
                            si = data(j + 1)
                            oldsr = 0.
                            oldsi = 0.
                            j = j - ifp1
        620 stmpr = sr
            stmpi = si

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        sr = ((twowr * sr) - oldsr) + data(j)
        si = ((twowr * si) - oldsi) + data(j + 1)
        oldsr = stmpr
        oldsi = stmpi
        j = j - ifp1
        if (j - jmin) 621, 621, 620
621 work(i) = (((wr * sr) - (wi * si)) - oldsr) + data(j)
        work(i + 1) = (((wi * sr) + (wr * si)) - oldsi) + data(j + 1)
630 i = i + 2
        wtemp = wr * wstpi
        wr = (wr * wstpr) - (wi * wstpi)
640 wi = (wi * wstpr) + wtemp
        i = 1
        do 650 j2 = i3, j2max, ifp1
            j3max = (j2 + np2) - ifp2
            do 650 j3 = j2, j3max, ifp2
                data(j3) = work(i)
                data(j3 + 1) = work(i + 1)
650 i = i + 2
        if = if + 1
        ifp1 = ifp2
C
C
C     COMPLETE A REAL TRANSFORM IN THE 1ST DIMENSION, N EVEN, BY CON-
C
C     JUGATE SYMMETRIES.
C
C
C
# 430 "fourth.for"
        if (ifp1 - np2) 610, 700, 700
# 435 "fourth.for"
700 goto (900, 800, 900, 701), icase
701 nhalf = n
        n = n + n
        theta = - (twopi / float(n))
        if (isign) 703, 702, 702
702 theta = - theta
703 wstpr = cos(theta)
        wstpi = sin(theta)
        wr = wstpr
        wi = wstpi
        imin = 3
        jmin = (2 * nhalf) - 1
        goto 725
710 j = jmin
        do 720 i = imin, ntot, np2
            sumr = (data(i) + data(j)) / 2.
            sumi = (data(i + 1) + data(j + 1)) / 2.
            difr = (data(i) - data(j)) / 2.
            difi = (data(i + 1) - data(j + 1)) / 2.
            tempr = (wr * sumi) + (wi * difr)
            tempi = (wi * sumi) - (wr * difr)
            data(i) = sumr + tempr
            data(i + 1) = difi + tempi
            data(j) = sumr - tempr
            data(j + 1) = (- difi) + tempi
720 j = j + np2
        imin = imin + 2
        jmin = jmin - 2
        wtemp = wr * wstpi
        wr = (wr * wstpr) - (wi * wstpi)
        wi = (wi * wstpr) + wtemp
725 if (imin - jmin) 710, 730, 740

```



```
c
# 520 "fourth.for"
860 j = j - np0
# 524 "fourth.for"
900 np0 = np1
    np1 = np2
910 nprev = n
920 return
    end
```